



EPRG-PRCI-APGA

## 23rd Joint Technical Meeting

Edinburgh, Scotland • 6–10 June 2022

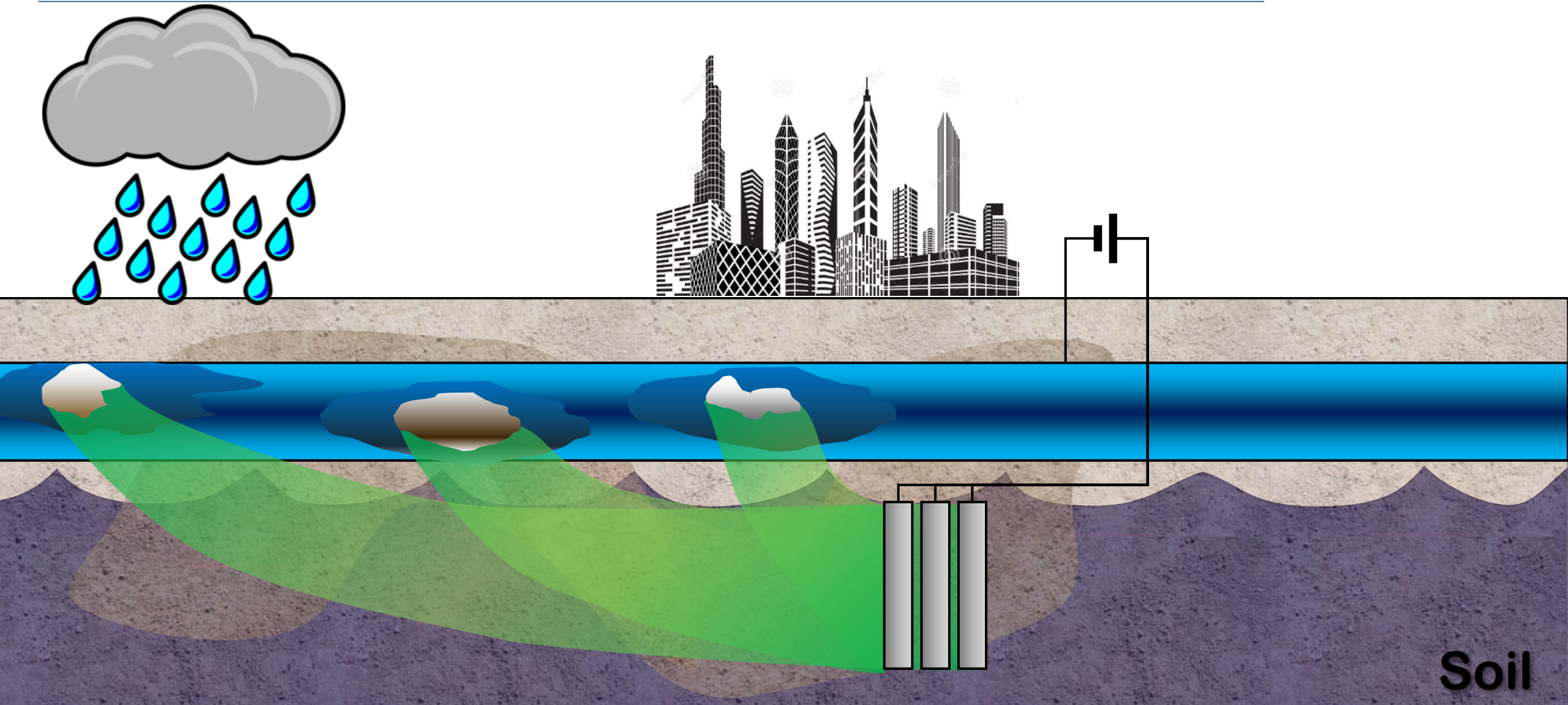
# CLOSED CONTROL LOOP FOR ICCP BASED ON CORROSION RATE SENSING

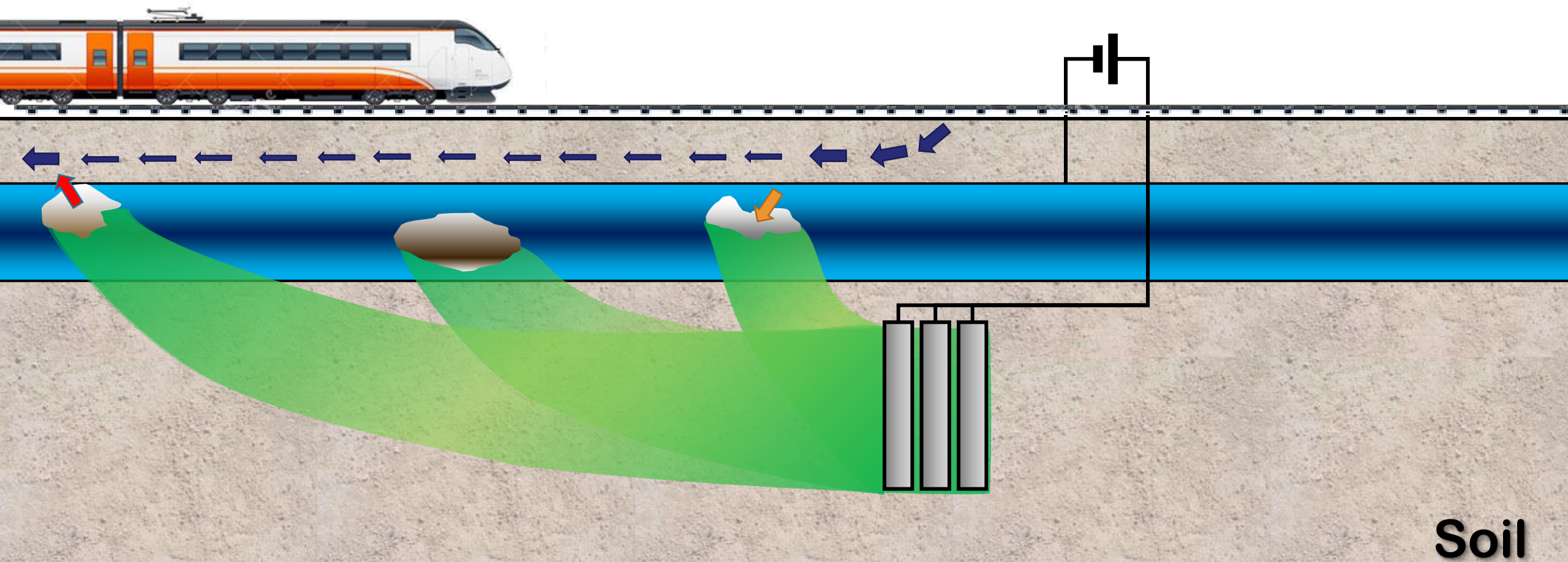
Facundo Bob Varela\* and Mike YJ Tan

Deakin University, School of Engineering and Institute for Frontier Materials, Victoria 3216, Australia

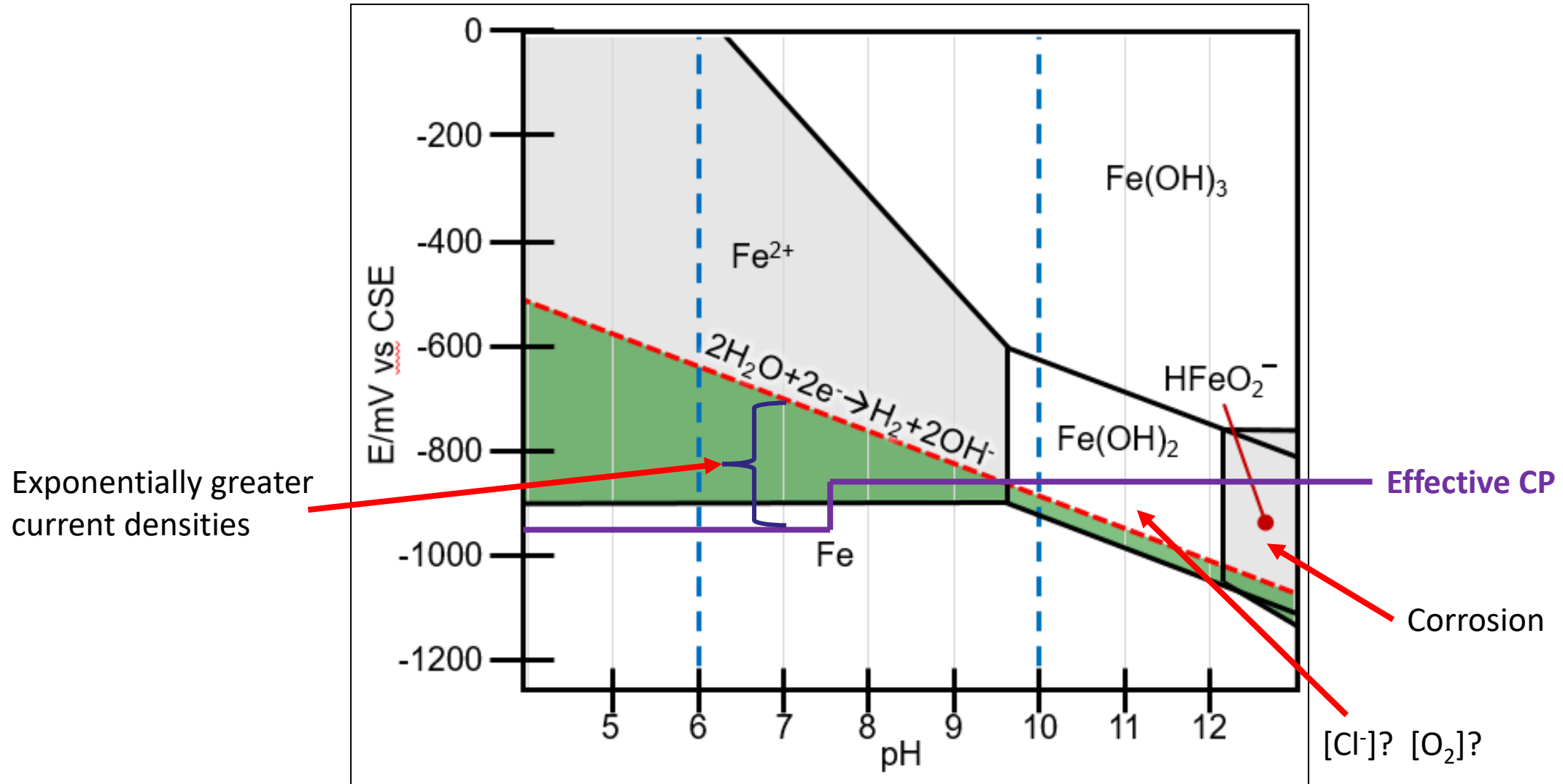


# Dynamic environmental conditions

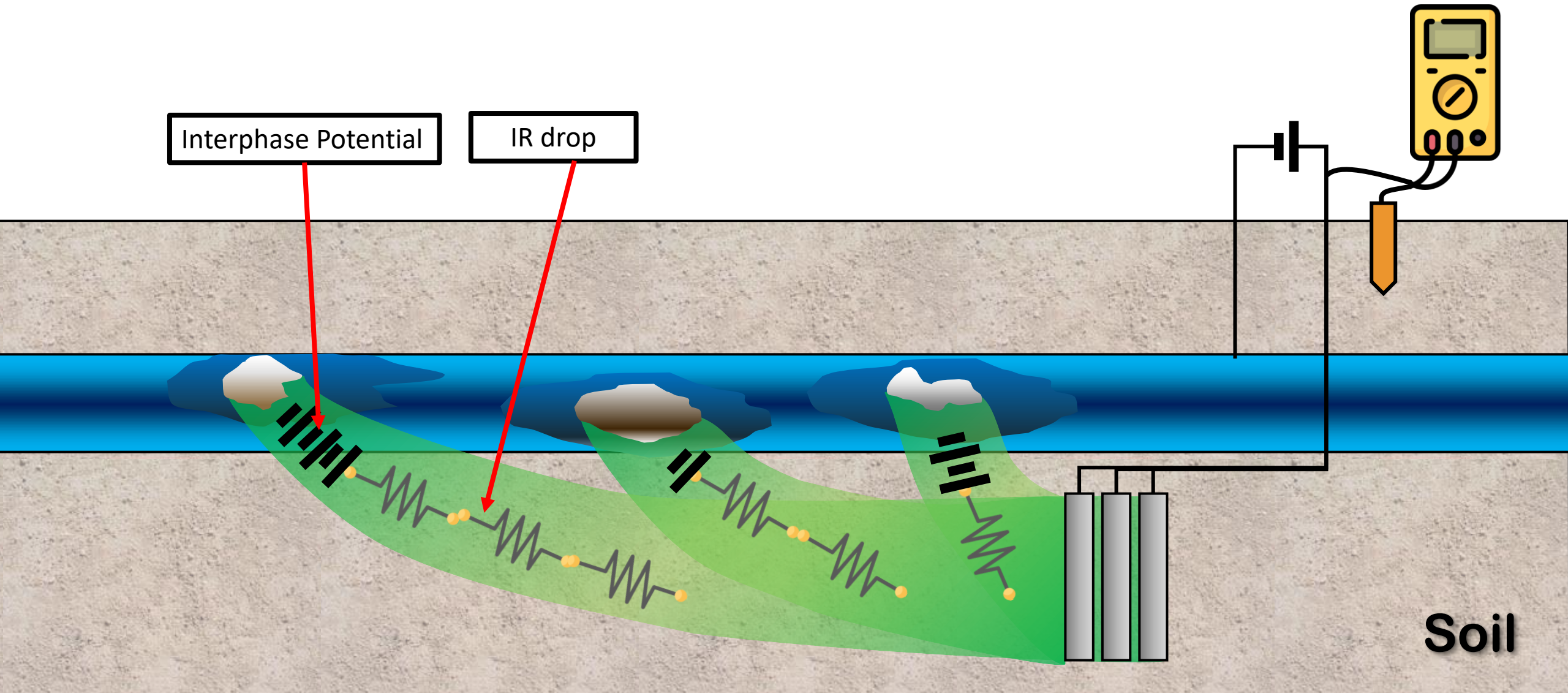




# Definition of succesful CP

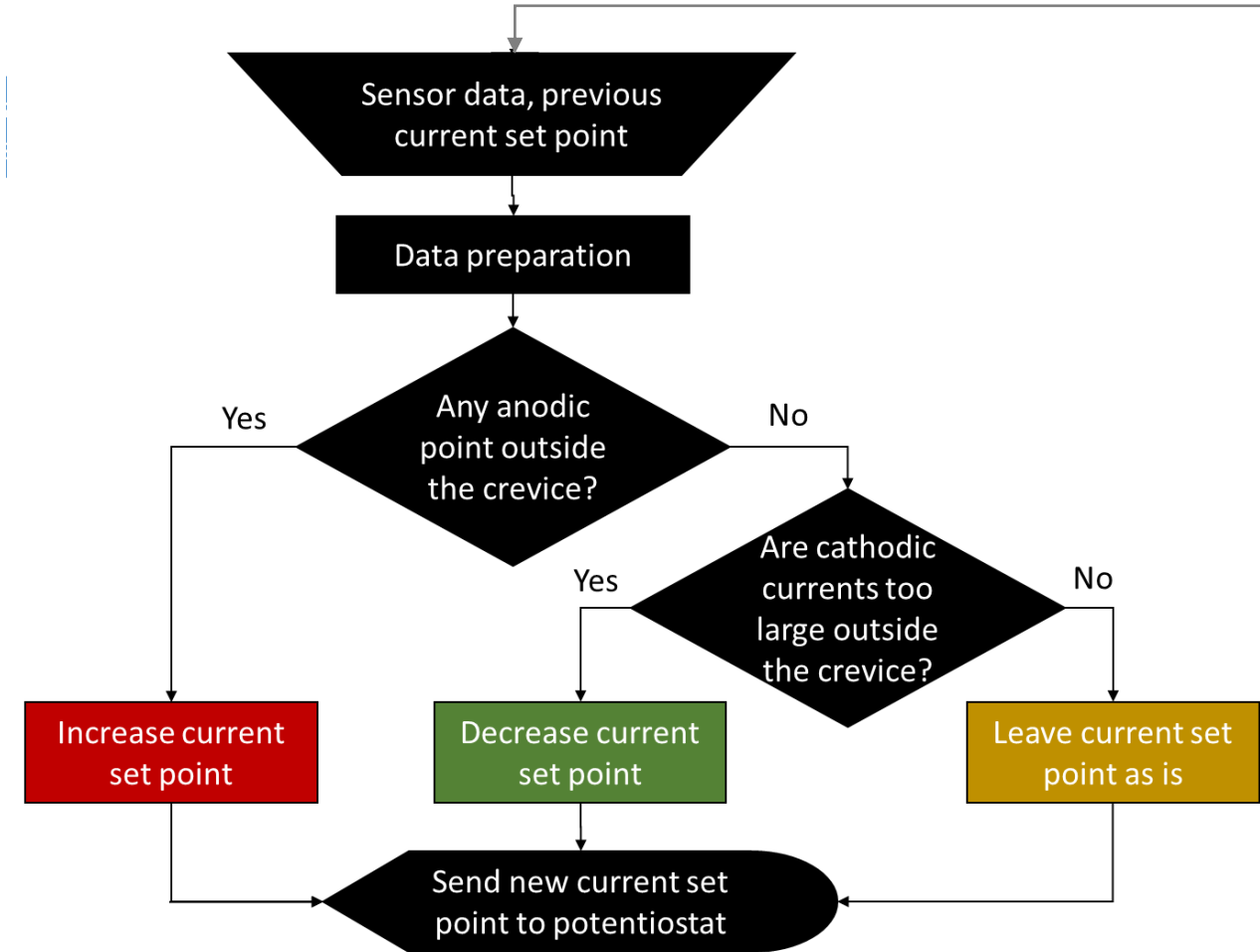
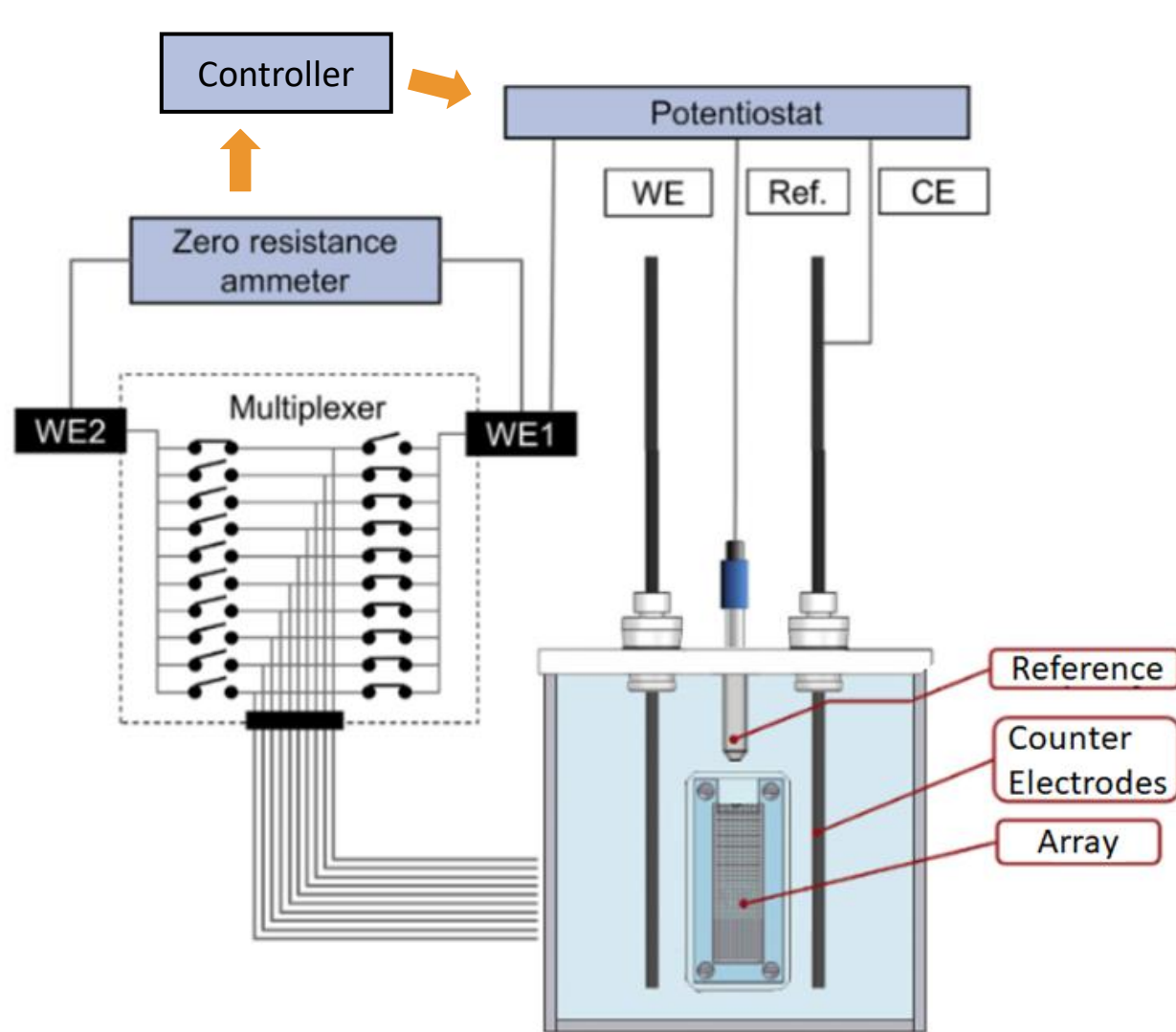


# The potential where?

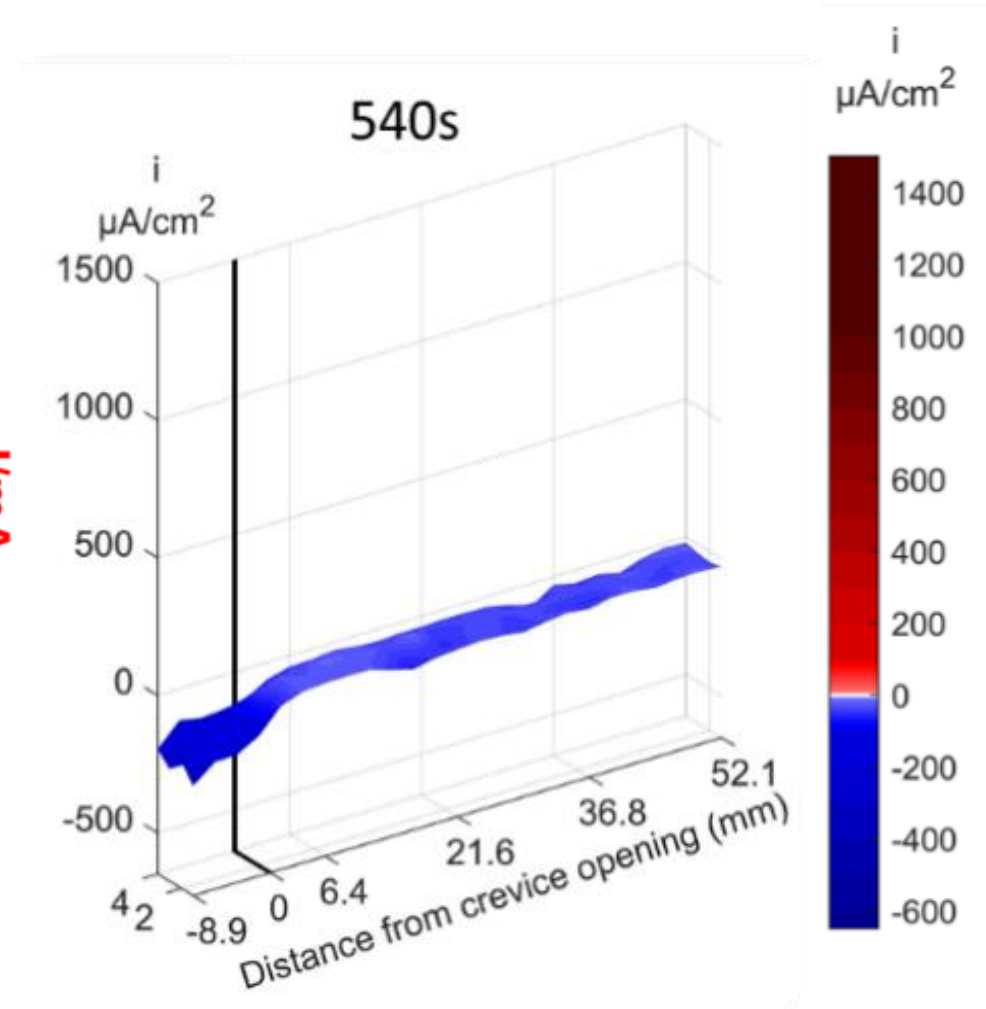
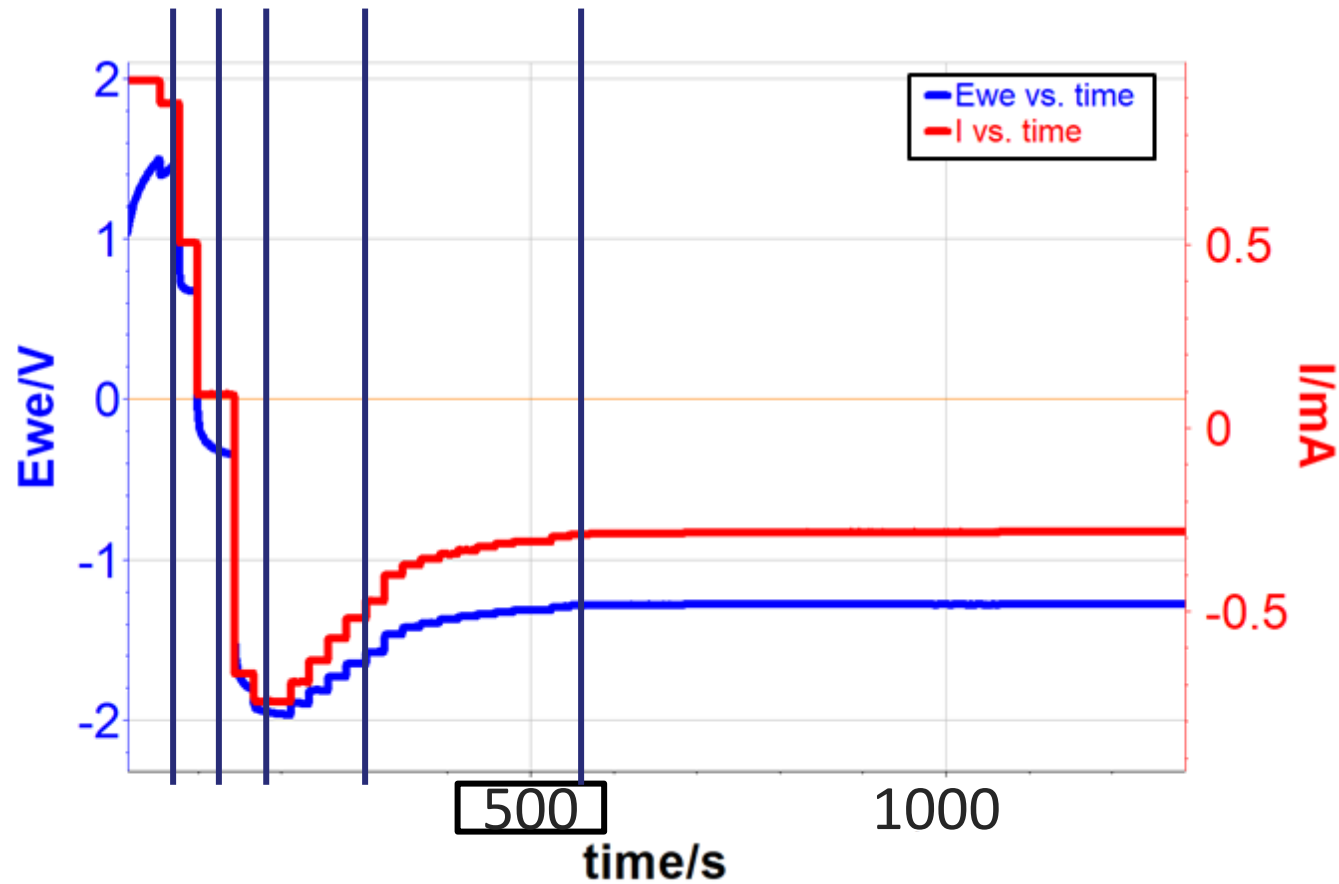




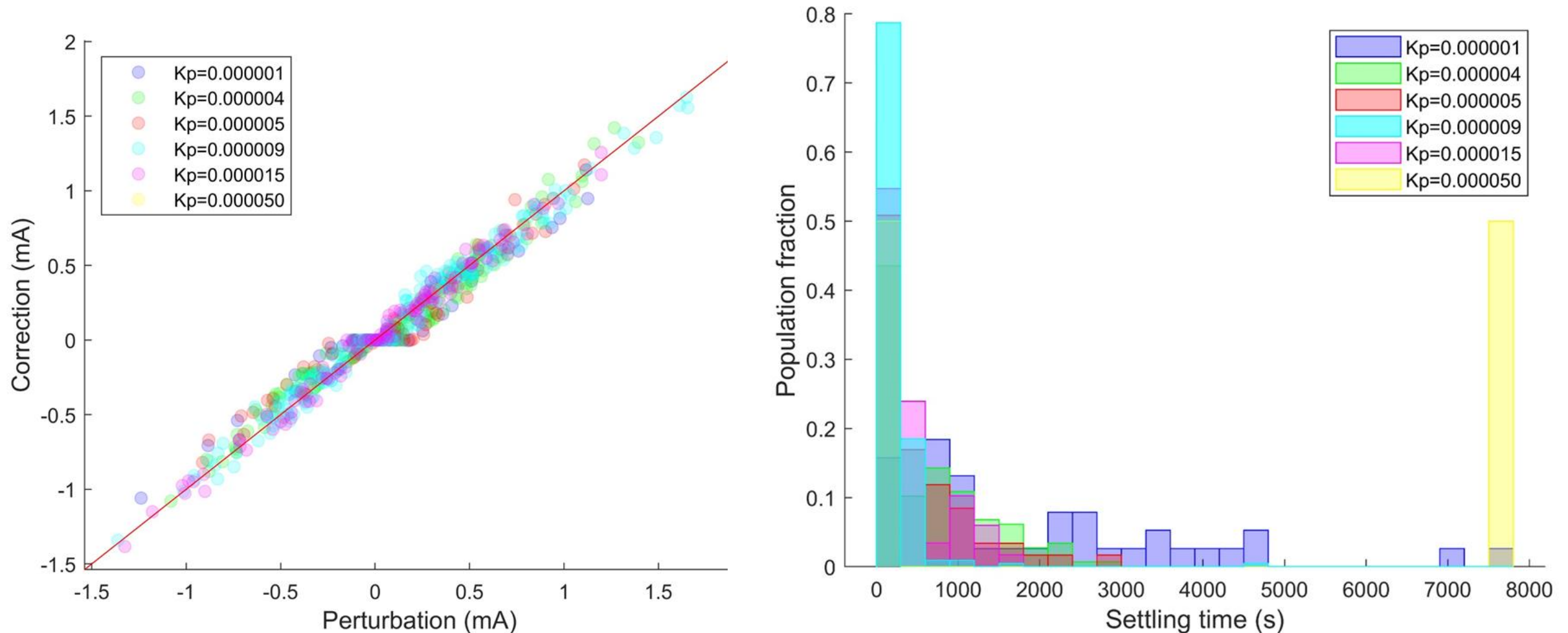
# Static and dynamic excursion compensation



# Excursion compensation from static conditions

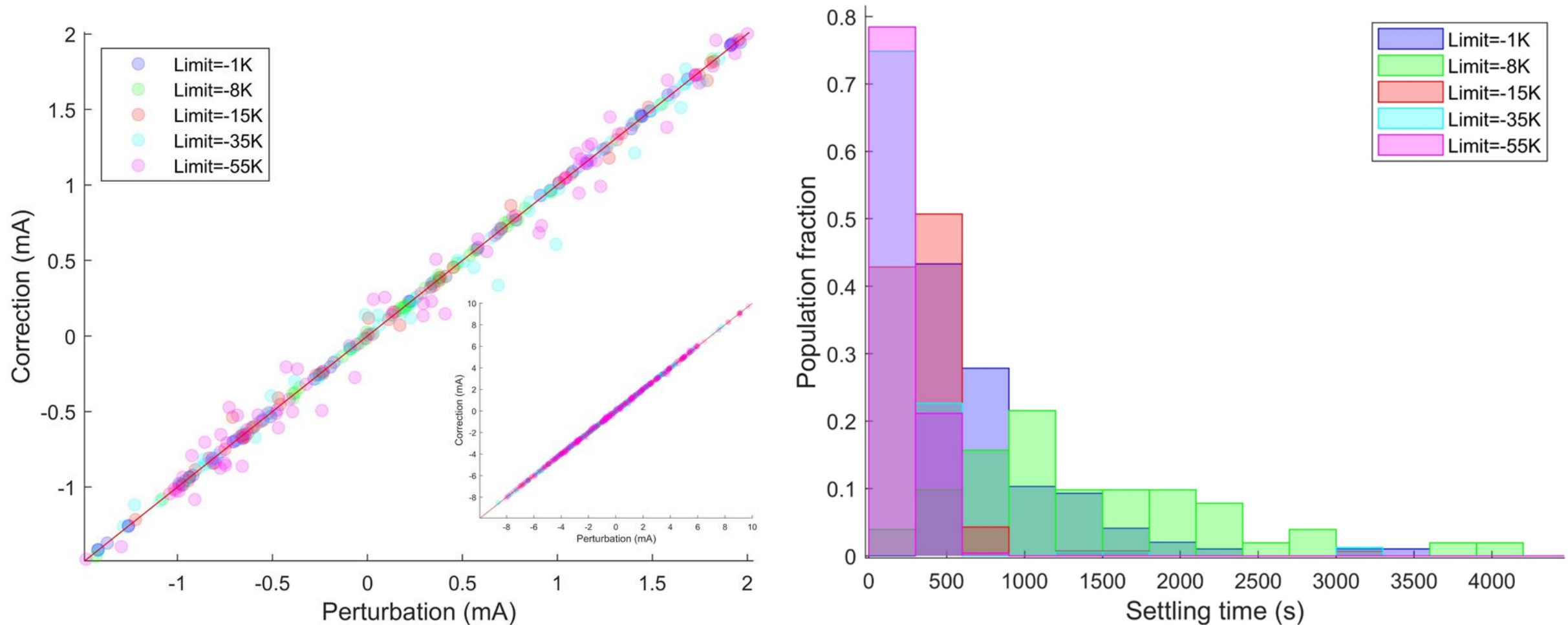


# Excursion compensation from static conditions

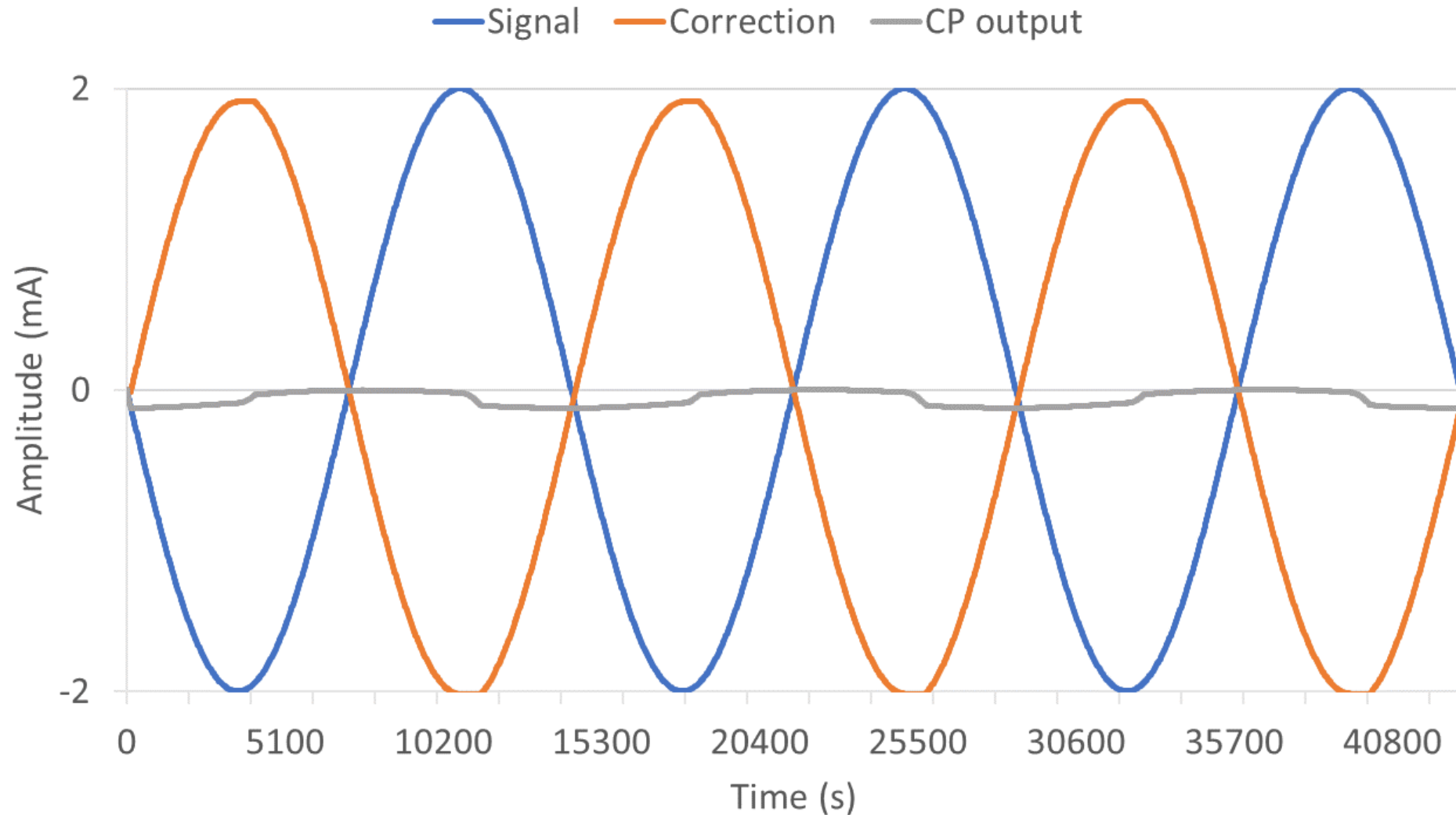




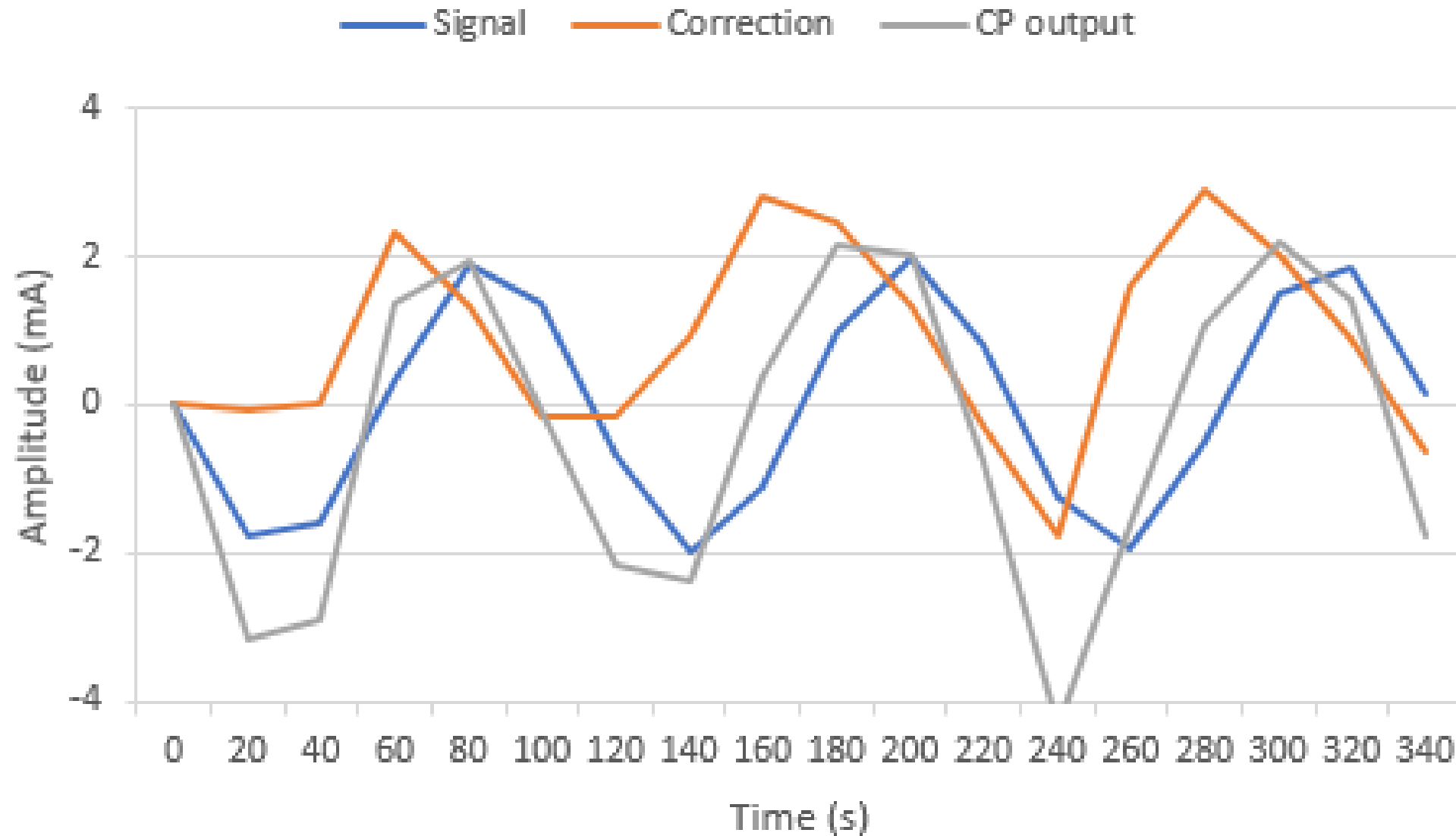
# Excursion compensation from static conditions



# Excursion compensation from Dynamic conditions

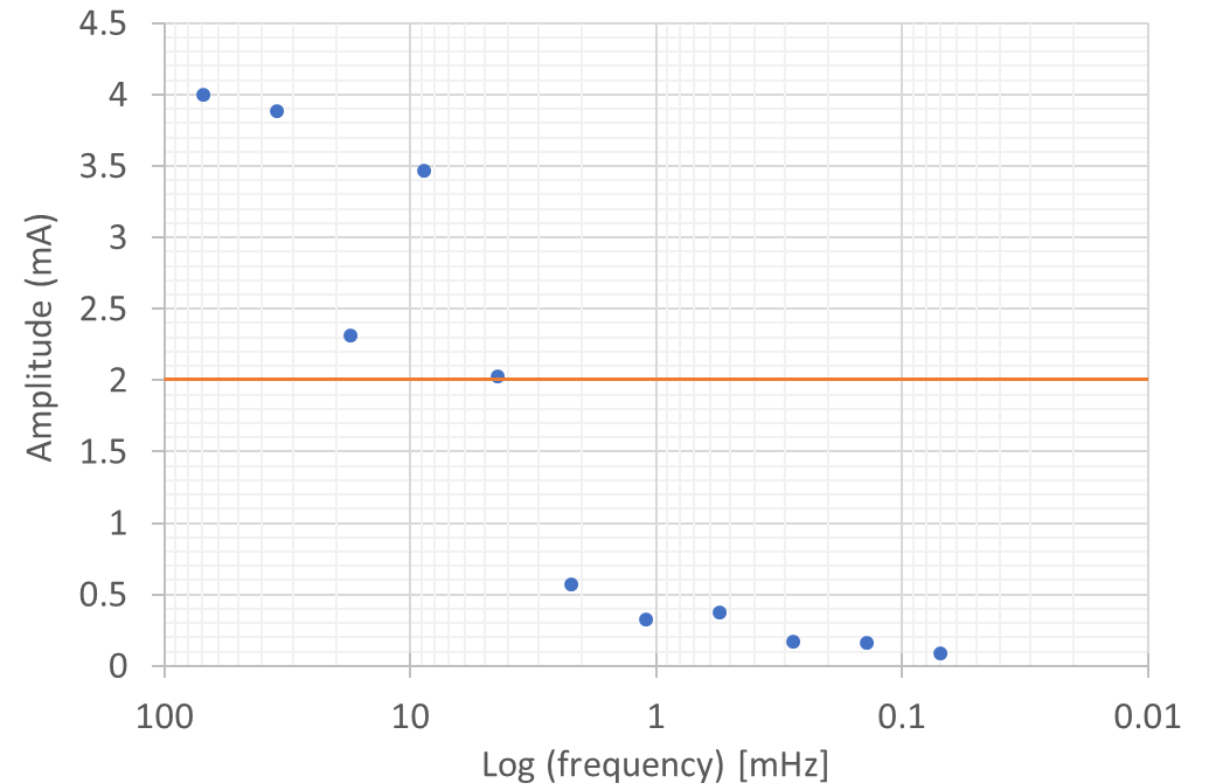
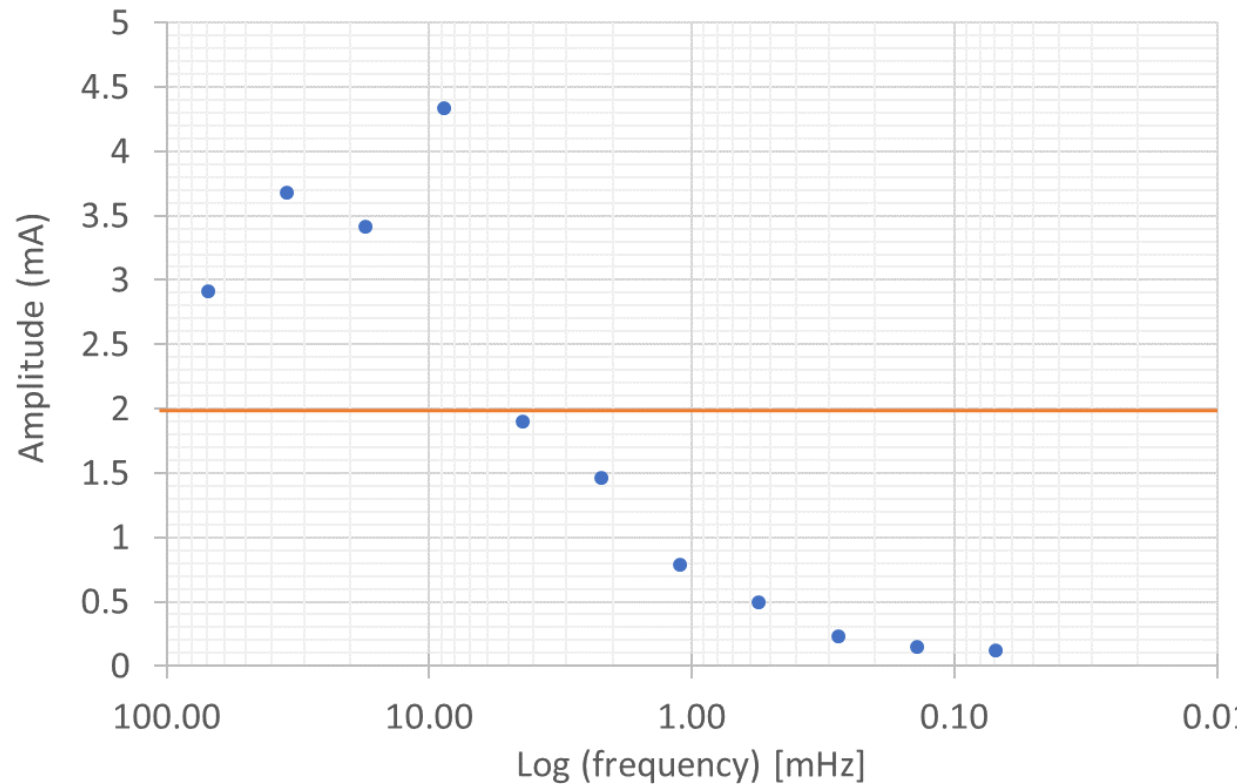


# Excursion compensation from Dynamic conditions

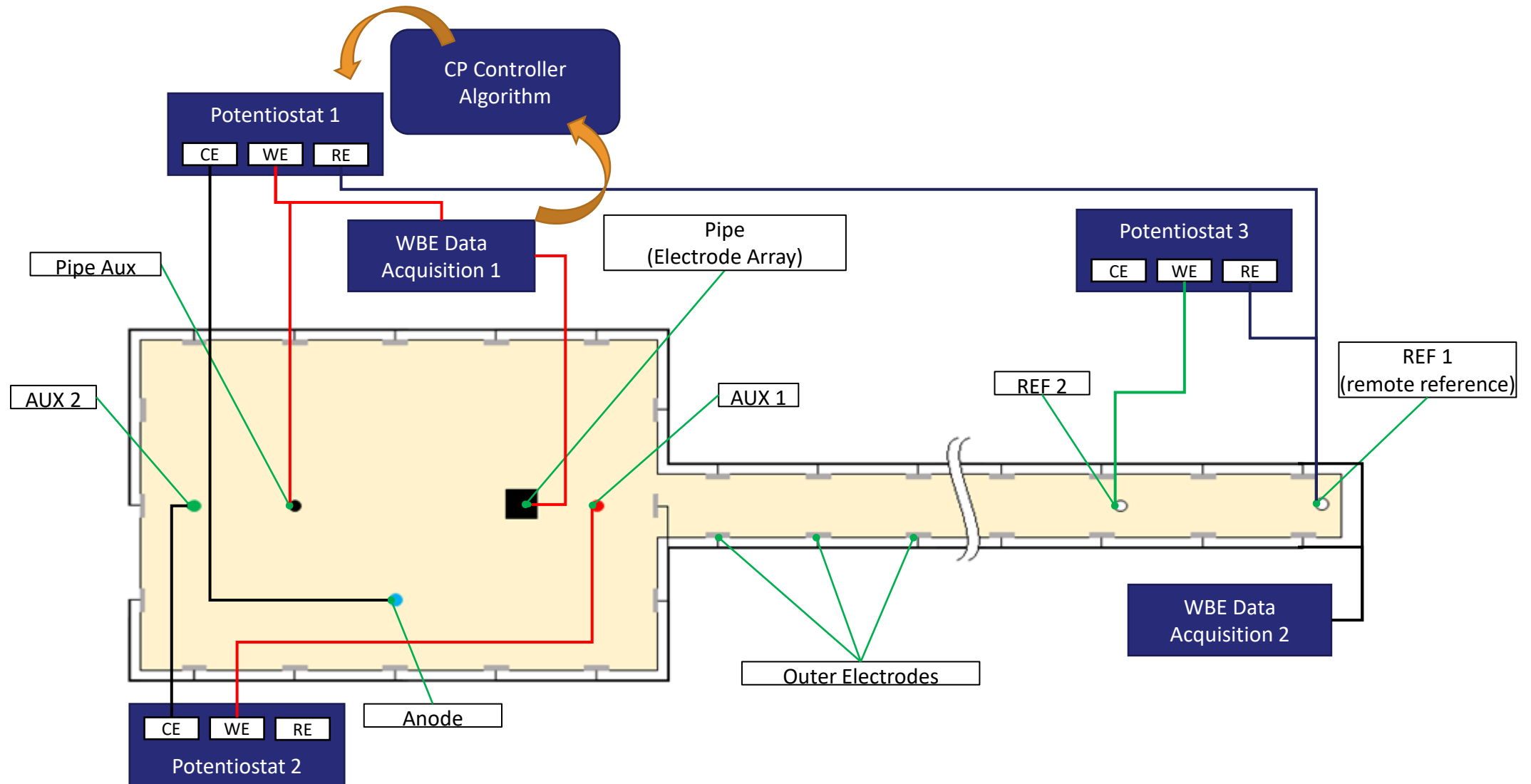




# Excursion compensation from Dynamic conditions

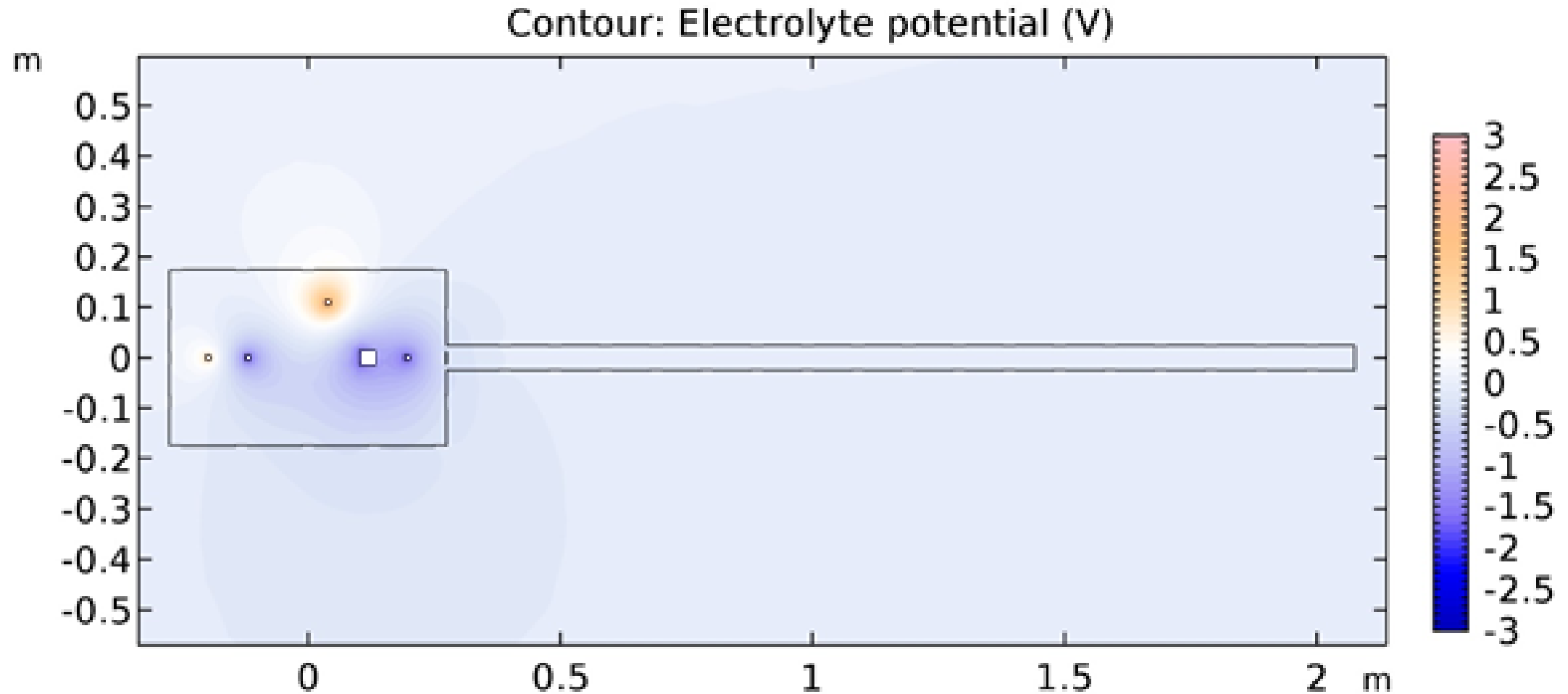


# Back to back test against potentiostatic control





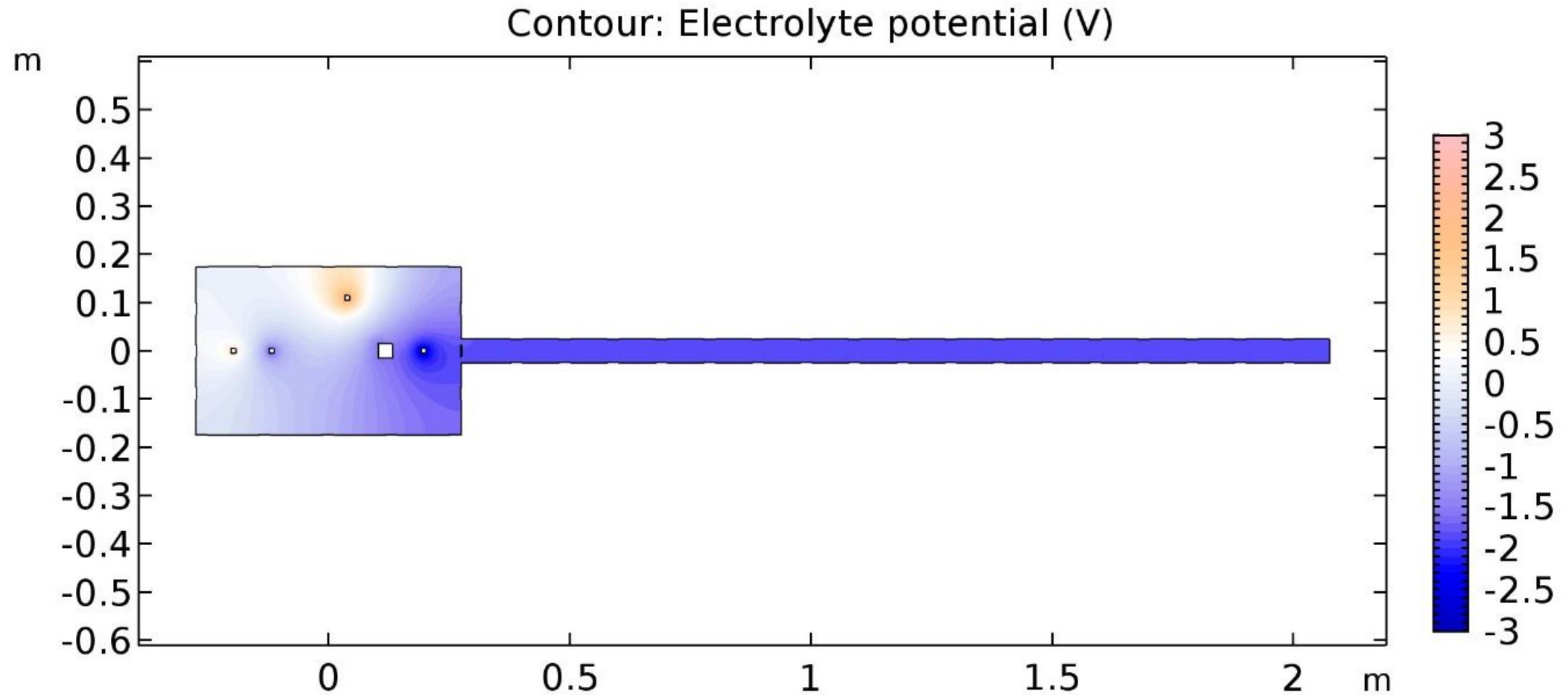
# Simulation of a semi-infinite media





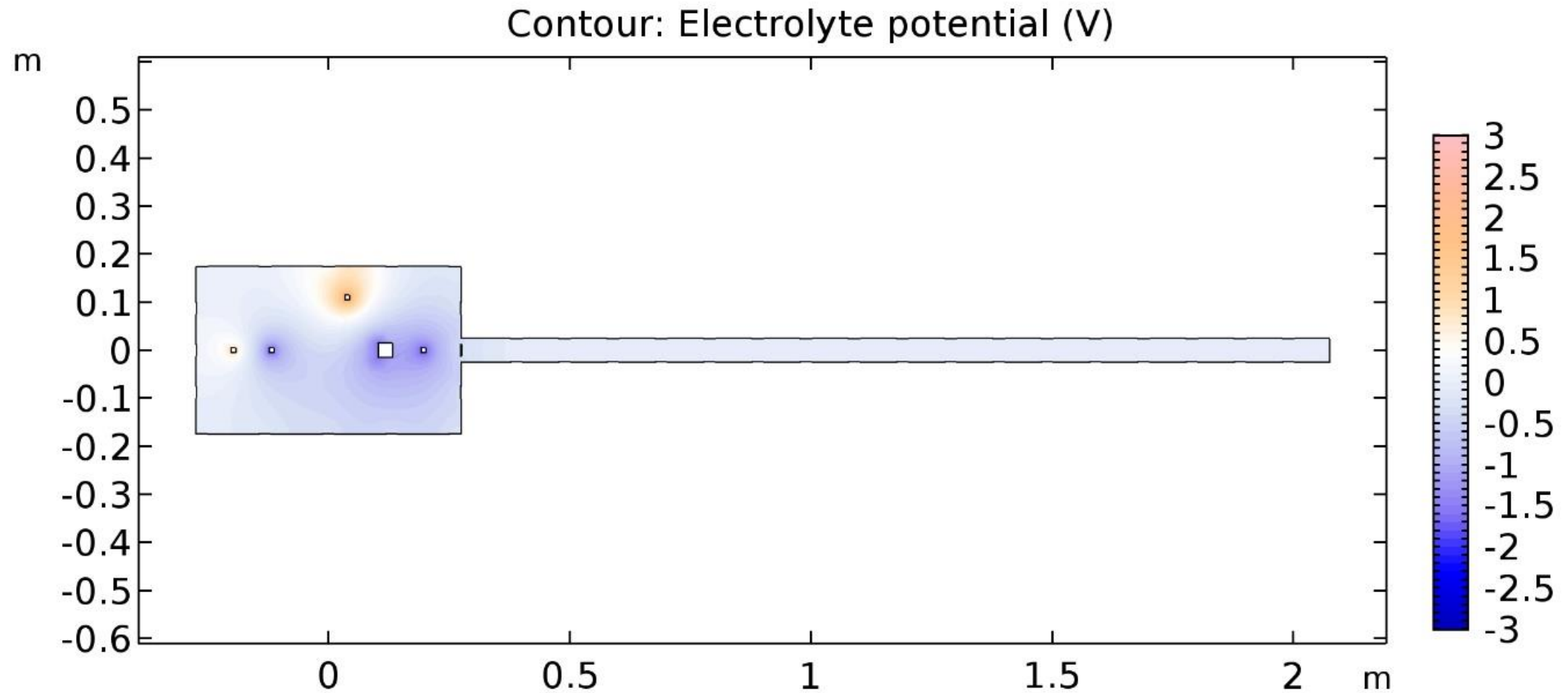


# Simulation of a semi-infinite media

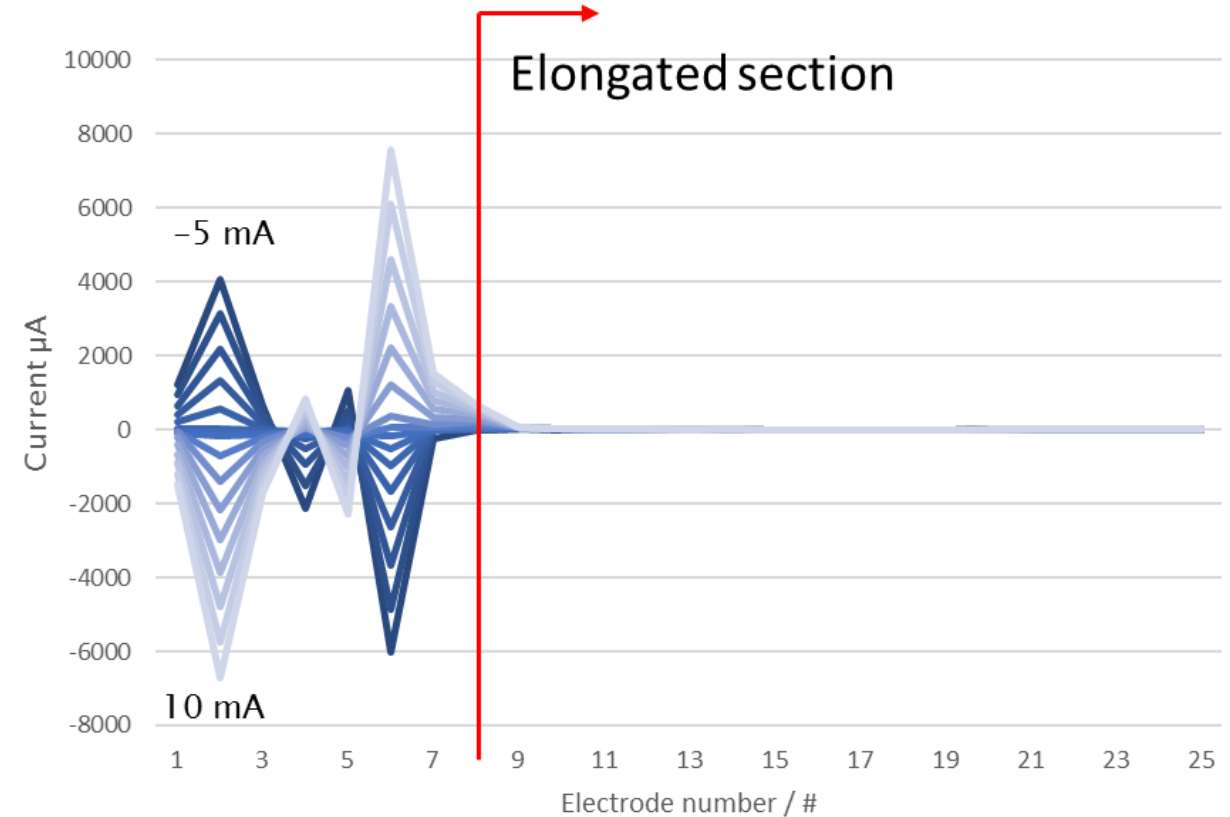
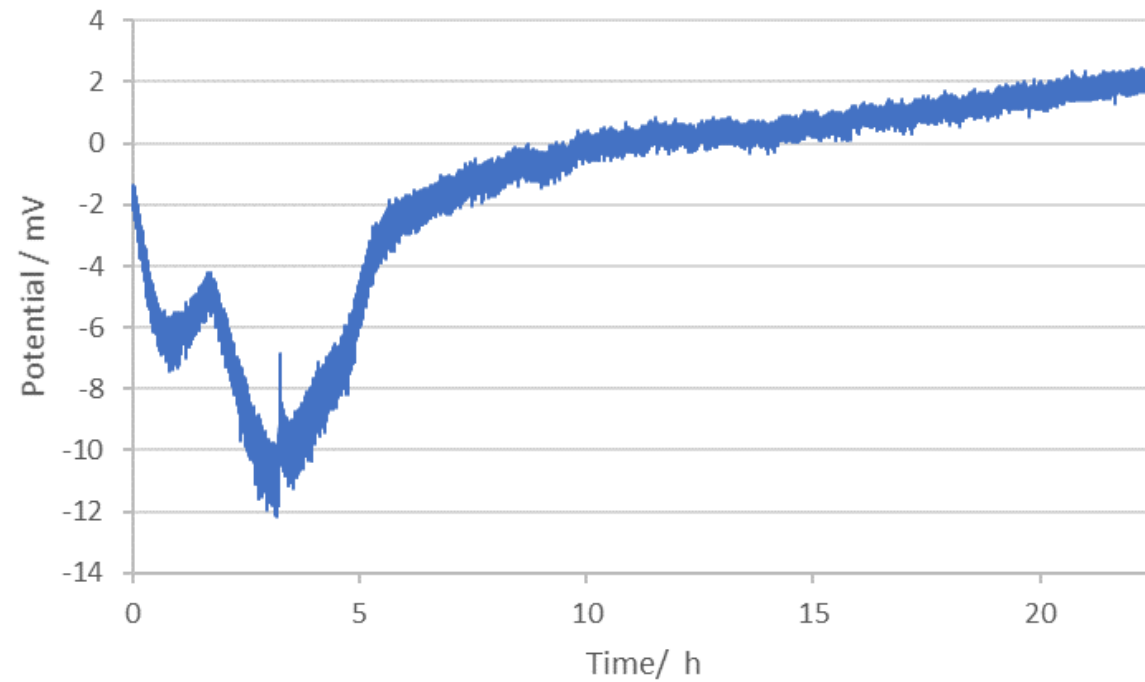




# Simulation of a semi-infinite media



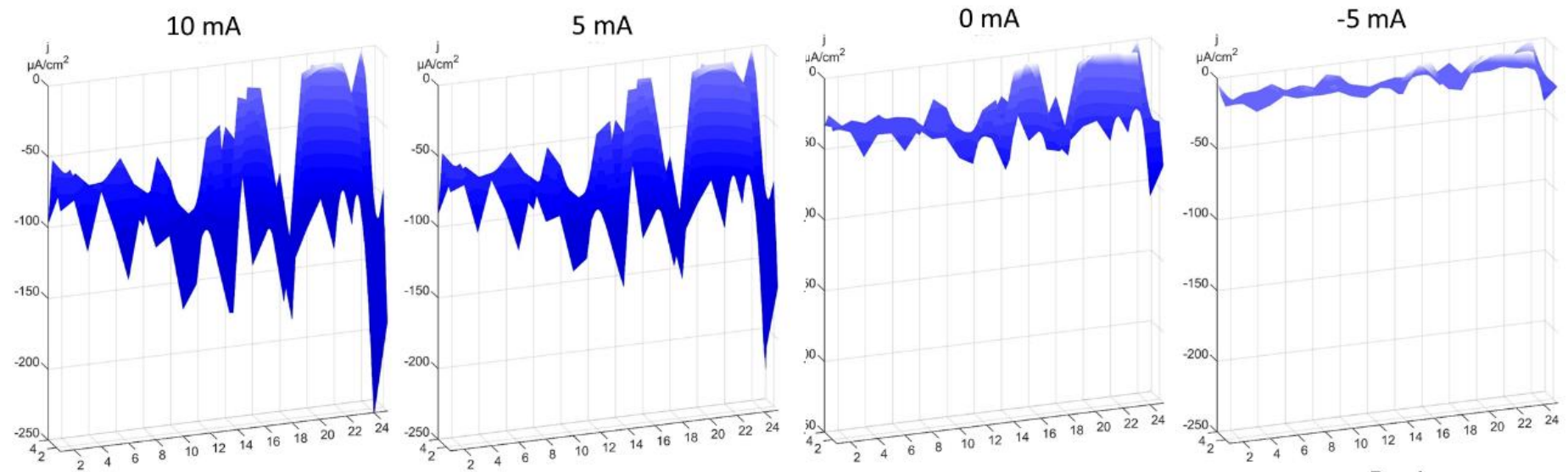
# Simulation of a semi-infinite media



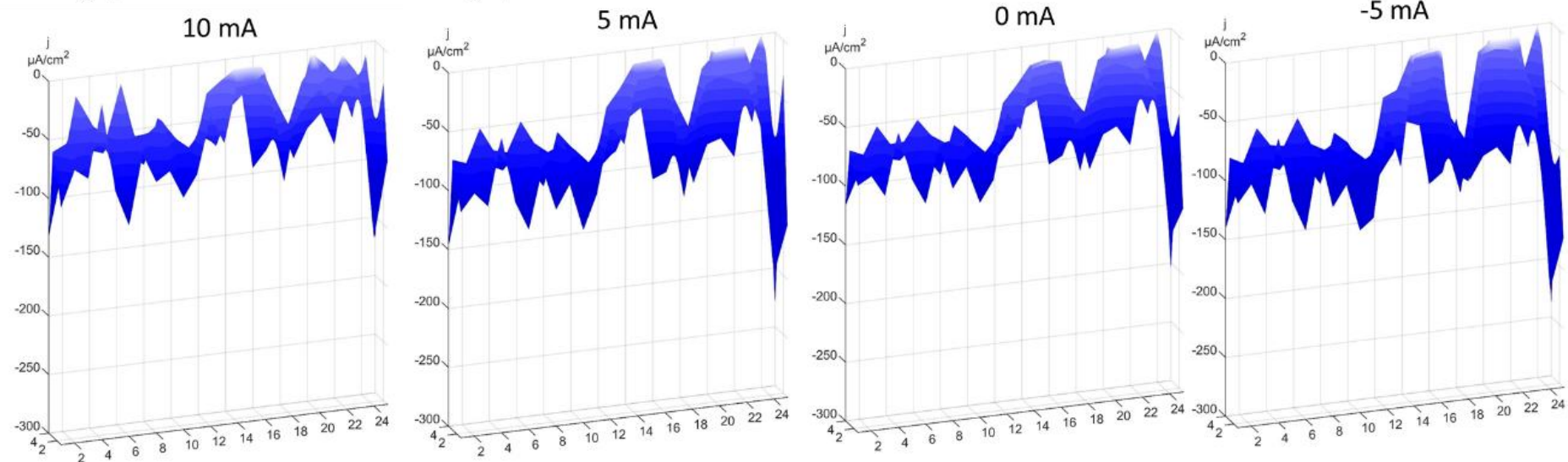


# Comparison: sand and test solution at 90% WHC

Potentiostatic  
closed loop

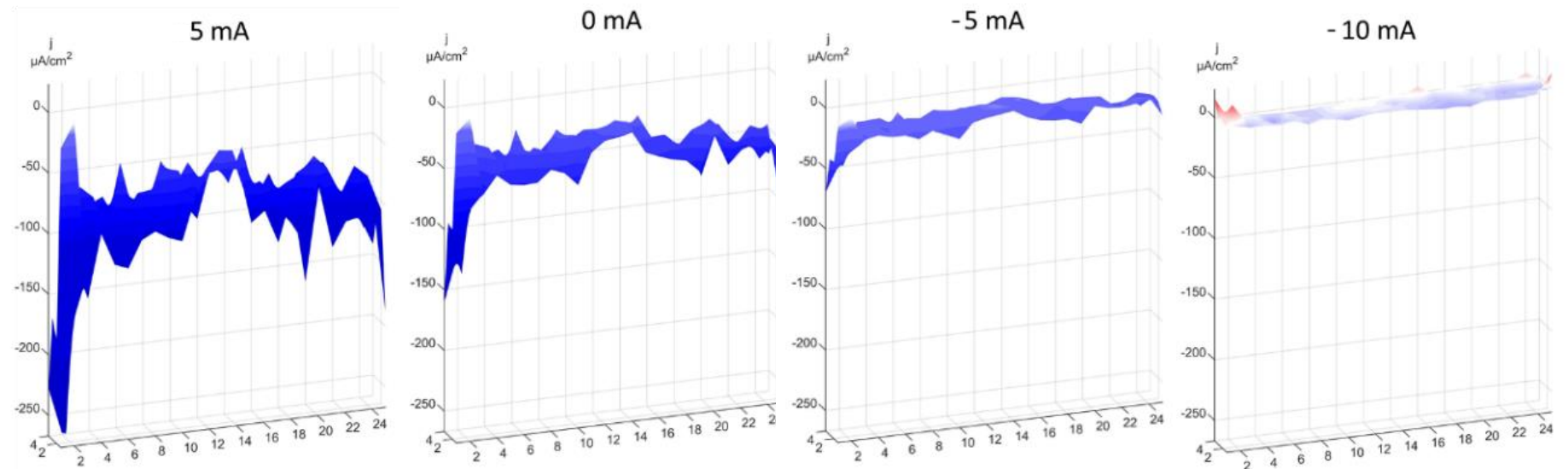


Corrosion rate  
closed loop

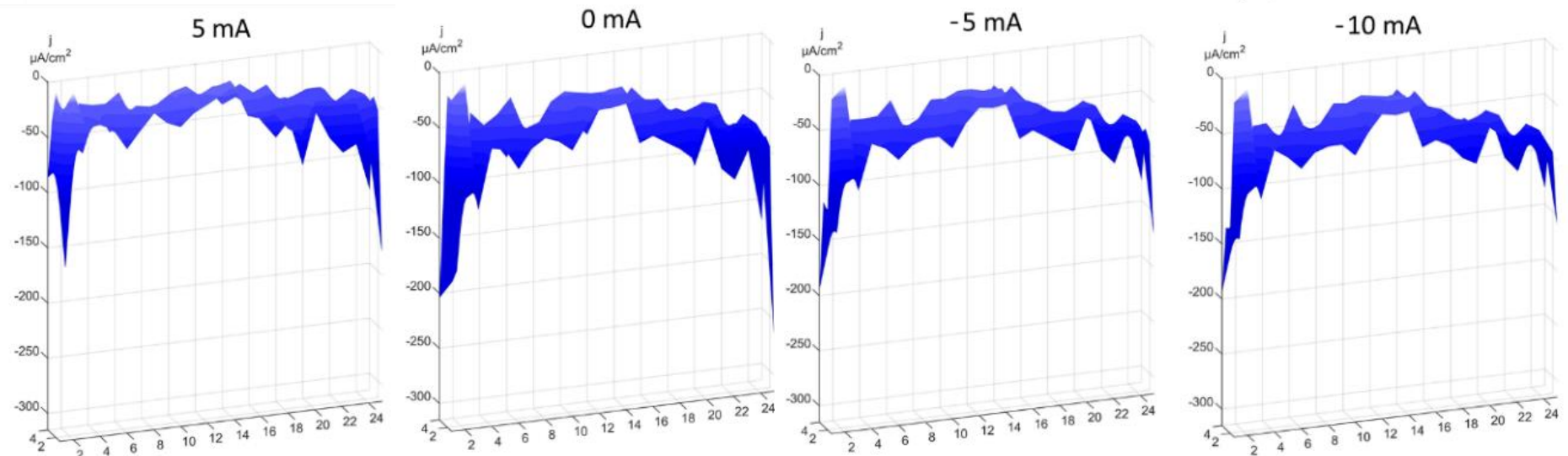


# Comparison: sand and test solution at 60% WHC

Potentiostatic  
closed loop



Corrosion rate  
closed loop





## Conclusions:

---

- The proof of concept was successful
- Excursion in CP can be compensated using proportional controllers
- Controller parameters must balance accuracy of compensations with settling time
- Under dynamic conditions, the bandwidth of the controller was limited by the sampling rate of the prototype
- The new control loop remained unmuted in stray current scenarios
- In same stray current scenario, potentiostatic control led to overprotection or underproduction





Future Fuels CRC is supported through the Australian Government's Cooperative Research Centres Program. We gratefully acknowledge the cash and in-kind support from all our research, government and industry participants.



**Australian Government**

**Department of Industry, Science,  
Energy and Resources**

**AusIndustry**  
Cooperative Research  
Centres Program

The background is an abstract geometric pattern composed of numerous triangles in various shades of blue and teal. The colors range from light, almost white, to dark navy blue. The triangles are of different sizes and are arranged in a way that creates a sense of depth and movement, with some triangles appearing to overlap others.

Thank you for your attention.