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Hard Spots NDE- Validation and Verification

Shree Krishna

Ravi Krishnamurthy

Blade Energy Partners



LEADING PIPELINE RESEARCH



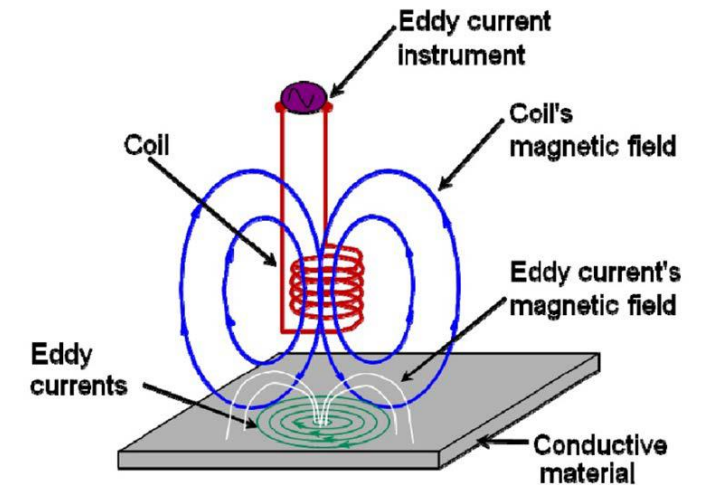
Phase I (March 2017)

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HARD SPOT: Localized regions of increased hardness in high strength Thermo-mechanically Controlled Processed (TMCP) line pipe grades

- Shallow small region of increased hardness ($>248 \text{ HV}_{10}$)

- Review of existing and emerging technologies for hard spot detection
- Five different providers were identified
 - *ExxonMobil*
 - *Innospection*
 - *Voestalpine-Fortec*
 - *Rosen*
 - *Rohmann*
- All the technologies were based on eddy current and electromagnetic principles (permeability, retentivity and coercivity), but with unique ways of hard spot identification



NDE 4-11 : Phase II (Aug 2018) – Focus of this Presentation

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- **Technologies were relatively new with no publicly available data**
- **Detection and Discrimination data were not publicly available**
- **Objective**
 - *Evaluate and assess the performance of the hard spot detection technologies*
 - *Conducted in two stages*
 - *Calibration testing*
 - *Blind trials testing*
 - *Finally, statistical evaluation of obtained results from the providers*

Outline

- **Calibration Phase**
- **Blind Trials Phase**
- **Statistical Evaluation**
- **Summary**

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Calibration Phase

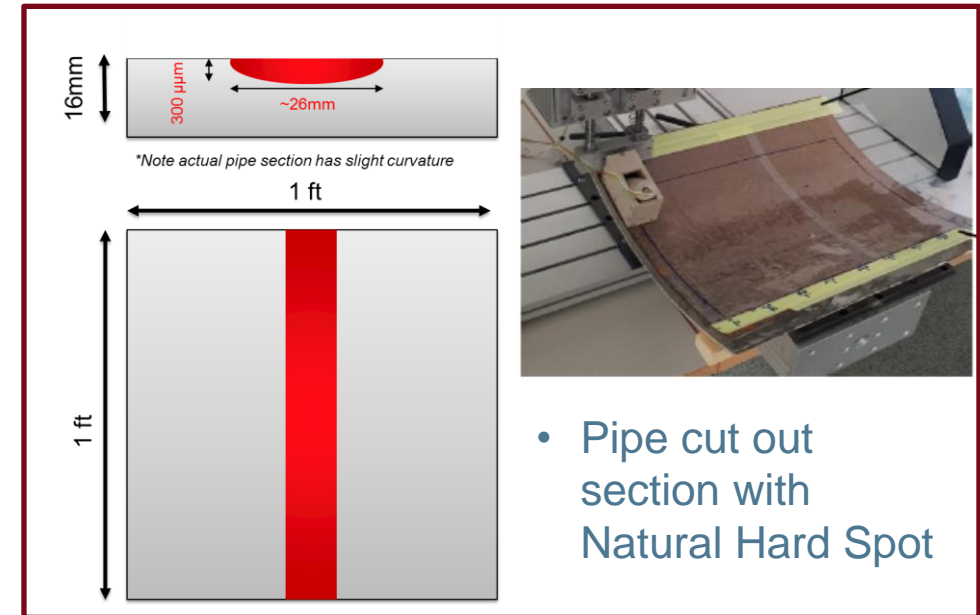


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Calibration

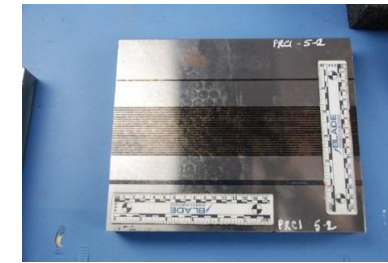
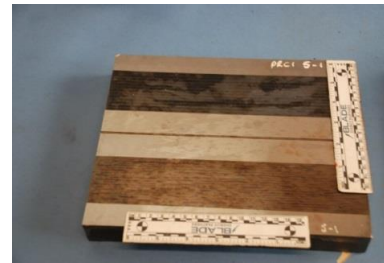
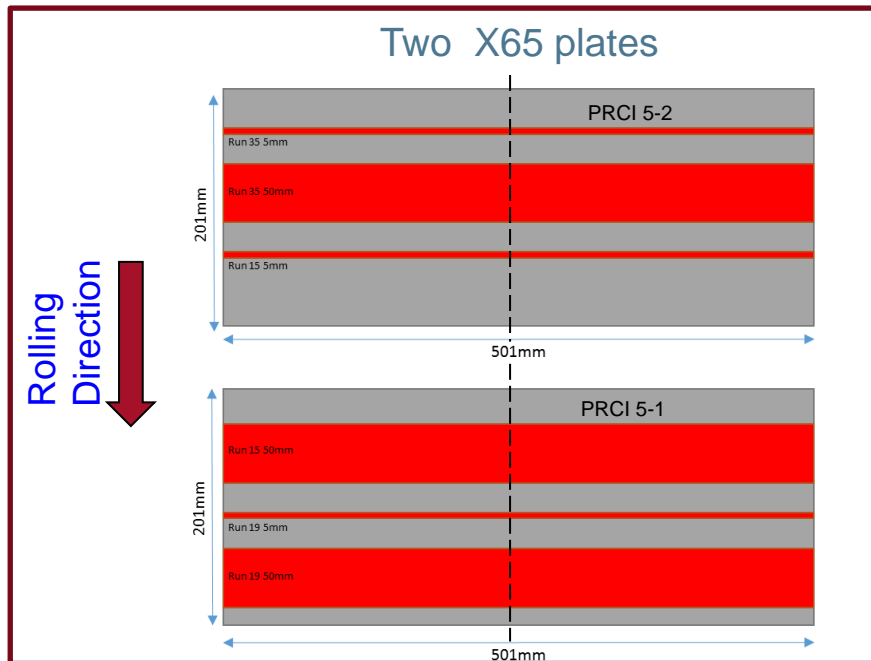
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- **Electromagnetic Principles distinguish hardened zones from base**
 - Material specific
- **Assess the technologies on artificially laser-hardened zones**
 - Compare with natural hard zones
- **Define the laser parameters appropriate for the blind trials**



Artificial Hard Spots

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Run#	Power, kW	Speed, m/min	Focal Position, mm	Spot Diameter, mm	Heat Input J/mm	Case Depth, μm
Run 35	3	20	60	4.8	0.493	75-90
Run 15	3	5	100	8.0	0.714	160-205
Run 19	3	20	40	3.25	1.09	125-127

- One half was circulated amongst technology providers to calibrate and evaluate their sensors
- Can they distinguish the natural hard spot and their comparison

CALIBRATION

	Run 35 (Tn) ~208 HV	Run 35 (Tk) ~219 HV	Run 15 (Tn) ~234 HV	Run 15 (Tk) ~279 HV	Run 19 (Tn) ~254 HV	Run 19 (Tk) ~ 306 HV	Natural Hardspots ~275 HV	Speed	Repeat'ty	Lift-off	Foot- print (mm)
Voestalpine	Red	Red	Green	Green	Green	Green	Green	S	R	~2mm	40x20; 20x10
Rohmann	Red	Red	Red	Green	Red	Green	Green	S	R	~2mm	10x10
Rosen	Red	Green	Red	Detected	Red	Green	Detected	-	R	~2mm	20x20
Innospection	Red	Red	Red	Detected	Red	Green	Detected	-	R	~1mm	2x2
Exxon-Mobil	Red	Red	Green	Detected	Green	Green	Detected	S	R	~2mm	20x40

*Probes used; actual sensor footprint is 10 x10 mm

Calibration Phase Conclusions

- Thin streaks (~5mm) hard spots were difficult to detect
- NDE response from Run 19 parameters are similar to the responses from natural hard spots
- Run 19 parameters produced hardness varying from 250-310 HV_{0.1} comparable to natural hard spot;
- Run 19 had a smallest spot diameter, which can be leveraged to create defects of varying sizes

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Blind Trials Phase

Creating artificial hard spots

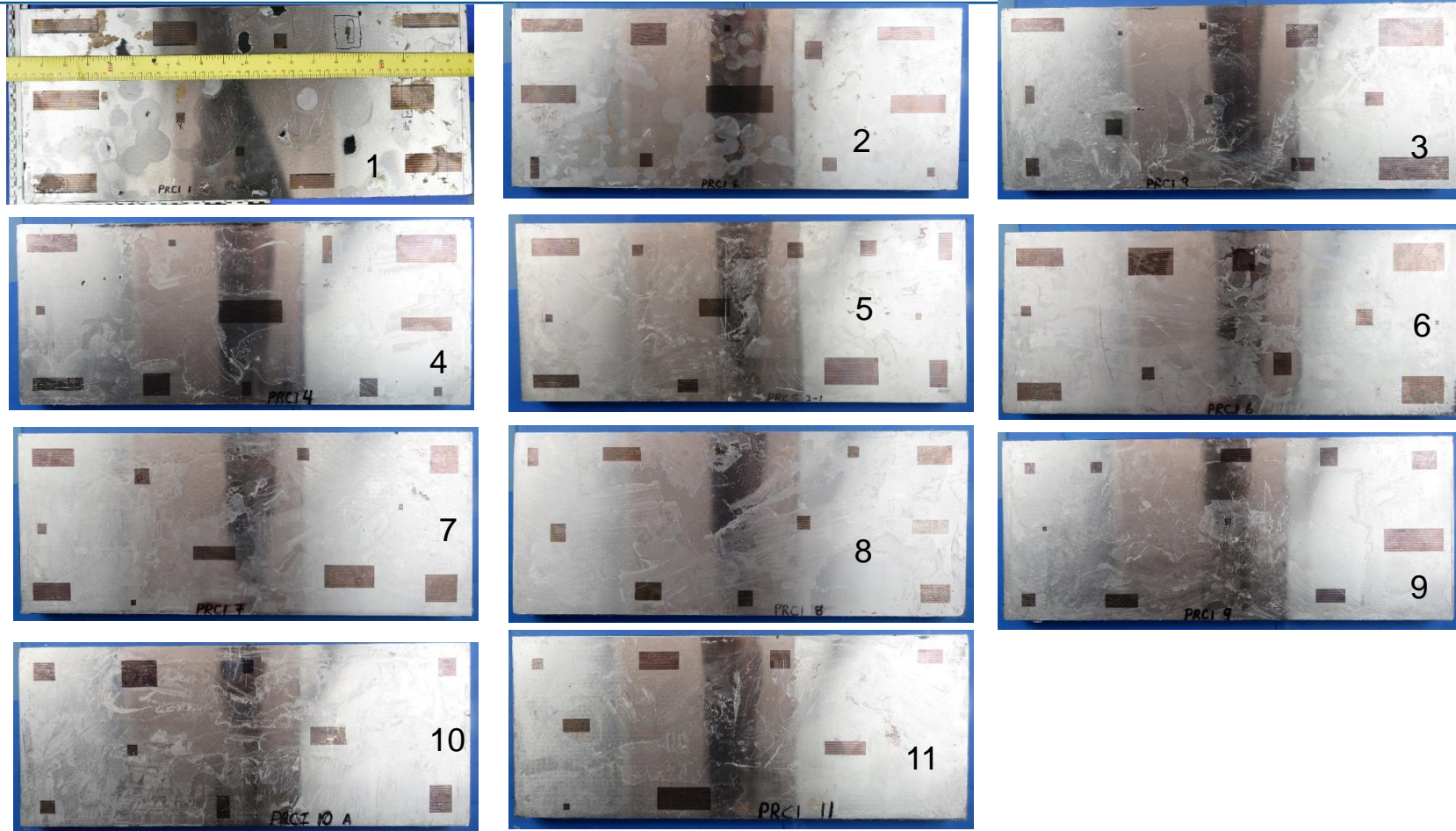
Verification / Validating defects

Execution and Assessment of Technologies



Test Plates

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X65 Plates (500 mm × 200 mm) with 121 hard spots with sizes varying from 5 to 75 mm. Length was verified before and after the trials.

Defect Concealment

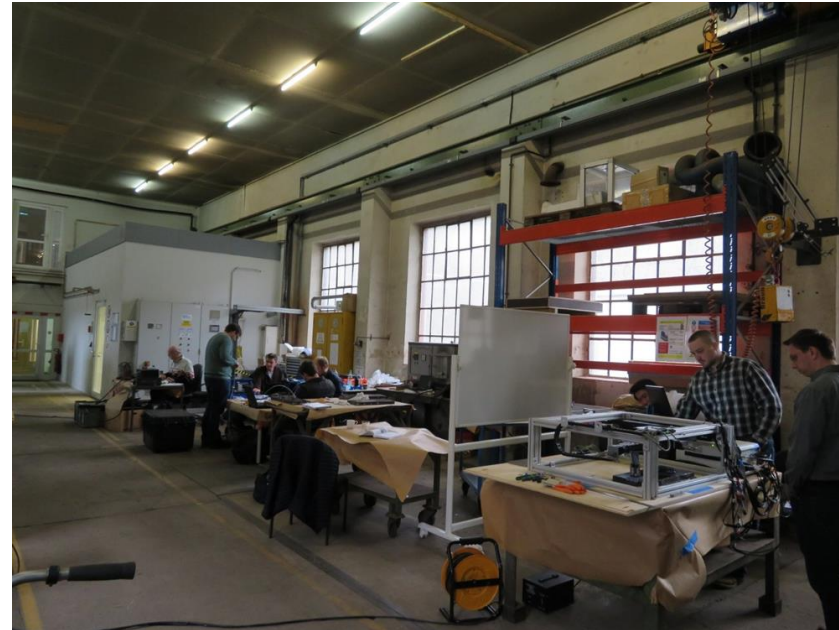


Plates surfaces were glued with 1mm thick black opaque ABS sheets

Blind Trials Phase

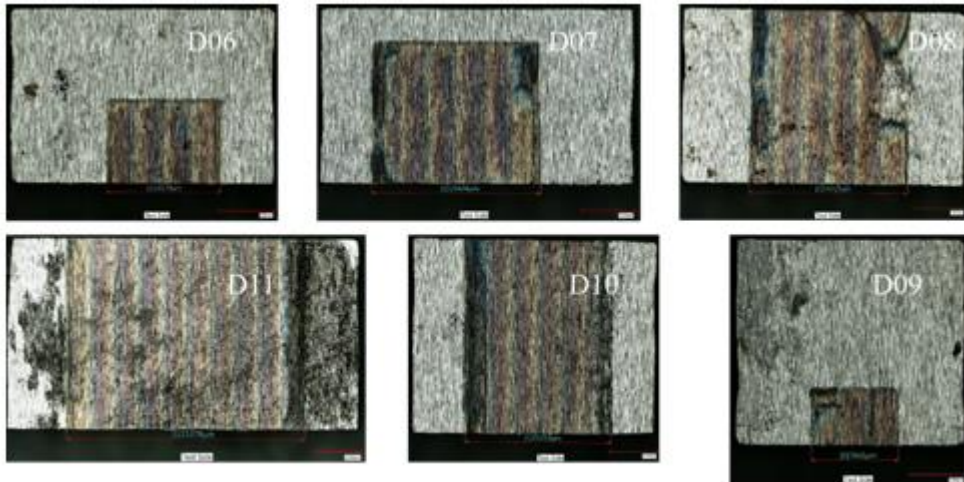
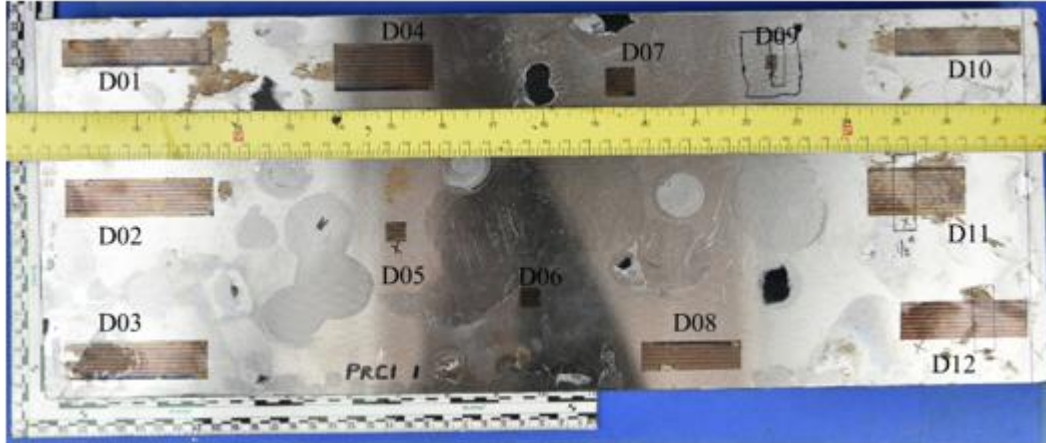
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- **Conducted at Dillinger Facility in Germany from 1st -12th April, 2019**
- **121 hard spots with sizes varying from 5 – 75 mm were fabricated (i.e., Run-19 parameters)**
- **Technology providers came to the facility and participated in turn to assess their technologies**
- **A detailed blind trials protocol was followed by all the providers. All the providers had 3 days to scan 11 surfaces and evaluate their technologies.**



Dillinger Hutte Facility, showing an overview of blind trials testing

Hard Spot Validation



Sectioned Defect	Defect Dimensions	Average	Maximum	Minimum	Top 5	Top 10
B01	Base Material	199	226	182	219	214
B02		199	229	185	217	214
D1	15 x 75	215	251	191	243	239
D2	20 x 75	225	291	188	288	283
D3	20 x 70	221	266	190	254	250
D4	25 x 50	228	293	173	288	283
D5	10 x 10	209	255	190	249	240
D6	10 x 10	208	269	178	262	253
D7	15 x 15	209	281	185	268	259
D8	15 x 50	206	267	181	261	251
D9	6 x 6	208	246	187	244	241
D10	15 x 65	210	288	179	272	266
D11	25 x 50	209	251	176	244	241
D12	20 x 65	222	299	181	285	279

Blind Trials Summary

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- **A detailed blind trials protocol followed by all the providers. Following runs from all technology providers:**
 - Eleven plate surfaces inspected at an optimum speed
 - One plate surface inspected at three different speed
 - One plate surface inspected thrice at their optimum speed
- **Results (including the defect maps and the defect dimensions) were provided to Blade for statistical analysis**

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Statistical Evaluation



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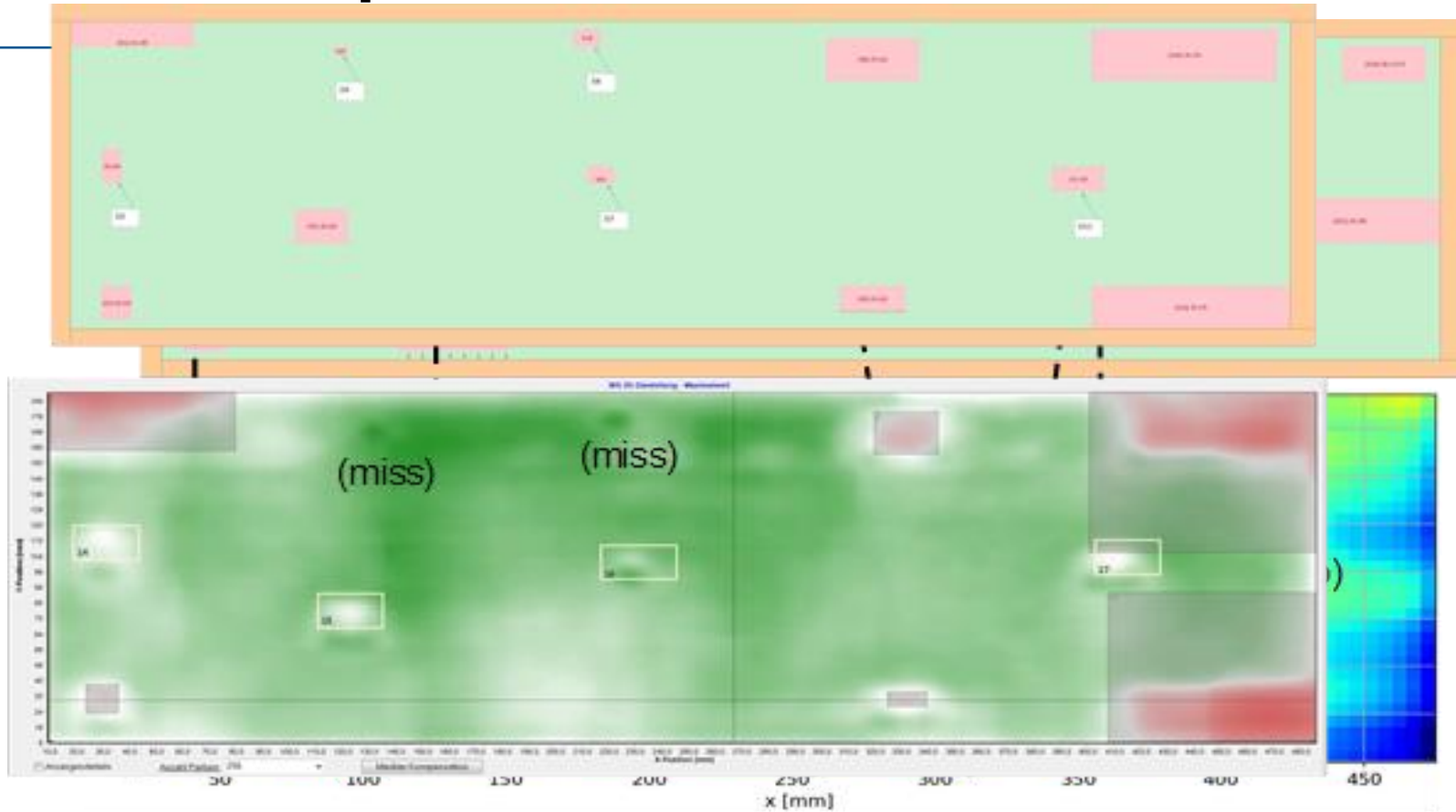
Statistical Evaluation

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- Defect map indicating the defect position were compared with the original defect layout
- Centroid position and defect dimensions (length, width) were compared with the original defects.
- Defects dimensions were divided into eight different size groups (5-10, 10-15, ..., 50+ etc.) and assessments were conducted for eight groups

Visual Comparison

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Reporting a defect either larger or smaller compared to original defect was considered a success
 Reporting a defect at a location with no original defect was considered a false call

Statistical Methods

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- **Probability of Detection**

- Success Rate

- *Detected compared with actual number of defects*

- Binomial Probability, $P(x)$, distribution Method

- *Used to determine the probability of finding “x” cases out of “n” measurements*

$$P(x) = C_x^n p^x (1 - p)^{n-x}$$

n = total number of measurements, x = number of “success,”

- **POFC (Probability of False Calls), frequency that tool falsely reports an anomaly**

Statistical Methods

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▪ Sizing Accuracy

- Measure of a NDE tool's ability to predict an anomaly's dimension (width and length)
- Tolerance in the measured dimension was calculated by mean size error and standard deviation

$$Tol_i = \mu + t_{\alpha/2} \sigma / \sqrt{N_i}$$

- Unity Graph and Regression Analysis

▪ Position Accuracy

- Measure of tool's ability to locate a hard spot and the relative error in reporting a defect location

POD (Success Rate)

- Defects were categorized in terms of sizes and the success rate of all the providers were evaluated.

Size Range	Provider "A"	Provider "B"	Provider "C"	Provider "D"	Provider "E"	Provider "F"
5<=x<=10	96%	83%	70%	43%	61%	96%
10<x<=15	100%	84%	100%	47%	68%	100%
15<x<=20	100%	100%	94%	71%	76%	100%
20<x<=25	100%	83%	100%	100%	100%	100%
25<x<=30	100%	100%	100%	83%	83%	100%
30<x<=40	100%	100%	100%	92%	100%	100%
40<x<=50	100%	100%	100%	100%	100%	100%
50<x<=75	100%	100%	100%	88%	88%	100%
Total	99%	93%	93%	73%	81%	99%

All the providers showed an overall success rate of 70% or higher. Provider "A" and "B" technologies have showed 99% success rate.

POFC (Probability for False Calls)

Technology	Total Defects (n)	False Calls (x)	POFC (x/n)
Provider 'A'	121	0	0%
Provider 'B'	121	2	1.7%
Provider 'C'	121	3	2.5%
Provider 'D'	121	38	31.4%
Provider 'E'	121	25	20.7%
Provider 'F'	121	1	0.8%

Generally low POFC

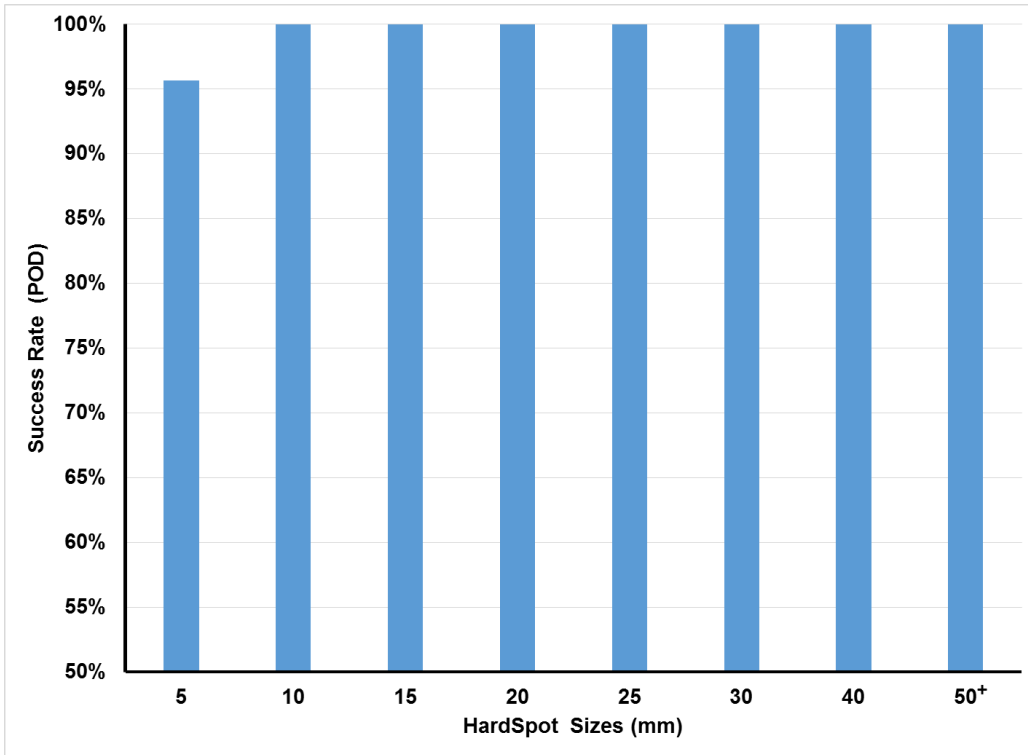
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Provider “A”



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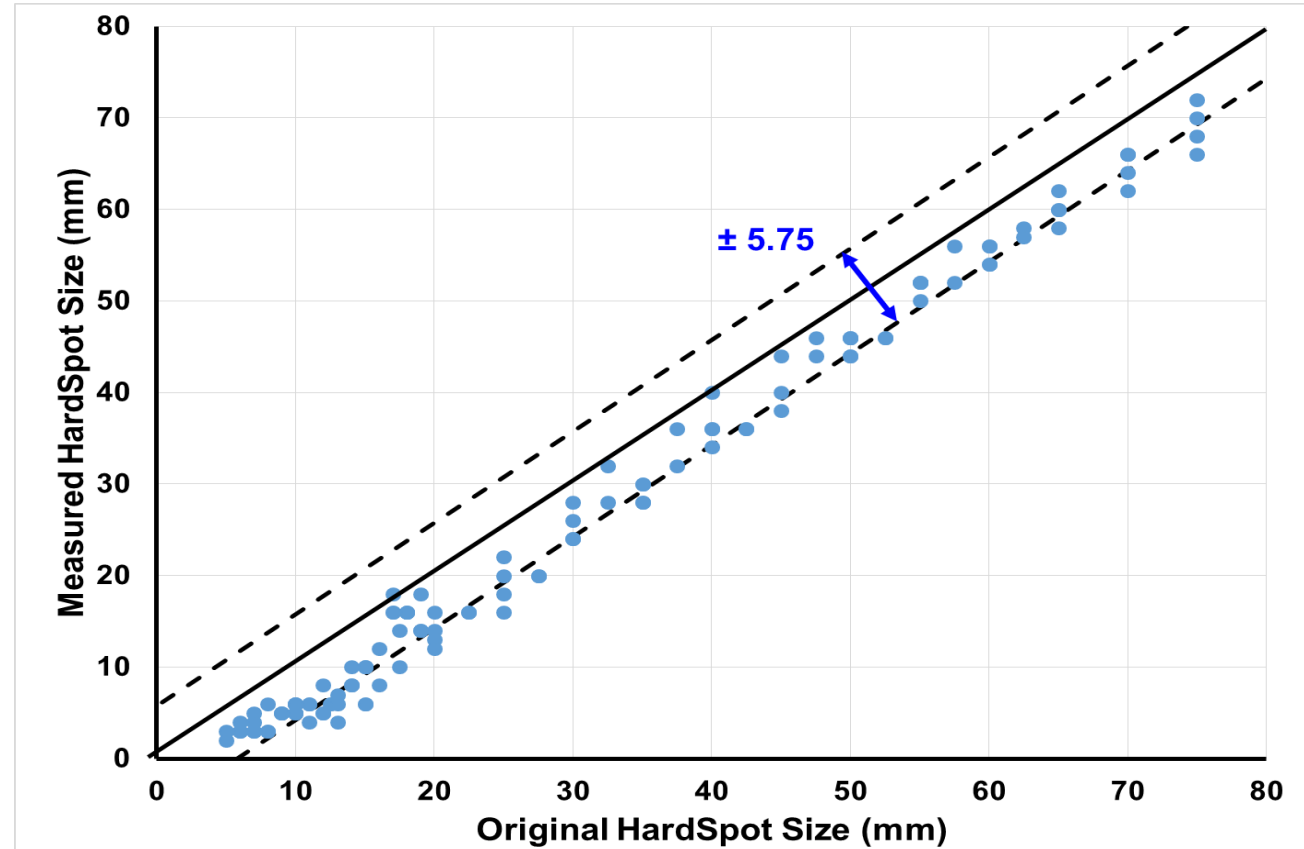
Probability of Detection (POD)



	Observations	Success	Binomial Probability	Binomial Confidence	C-P Lower	C-P Upper
5<=x<=10	23	22	88%	95%	81%	100%
10<x<=15	19	19	85%	95%	85%	100%
15<x<=30	29	29	90%	95%	90%	100%
30<x<=50	24	24	88%	95%	88%	100%
50<x<=75	26	26	89%	95%	89%	100%
Total	121	120	98%	95%	96%	100%

Provider "A" can detect 5+ mm hard spots with a certainty of 80% and with 95% confidence

Sizing Accuracy – Unity Plot



- Original versus Measured Hard spot size

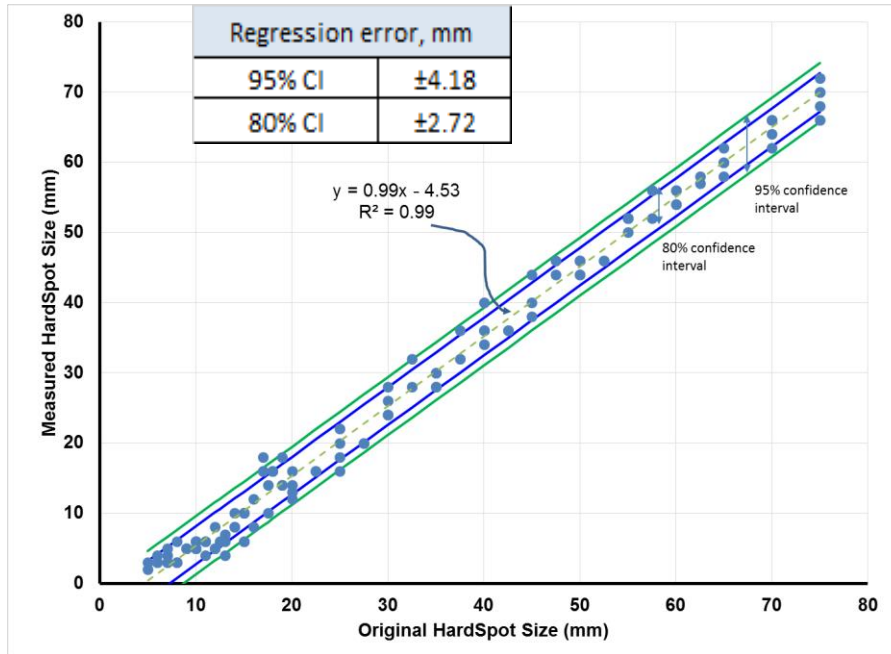
Sizing Accuracy

Tolerance: $\mu \pm t_{\alpha/2} \sigma / \sqrt{n}$

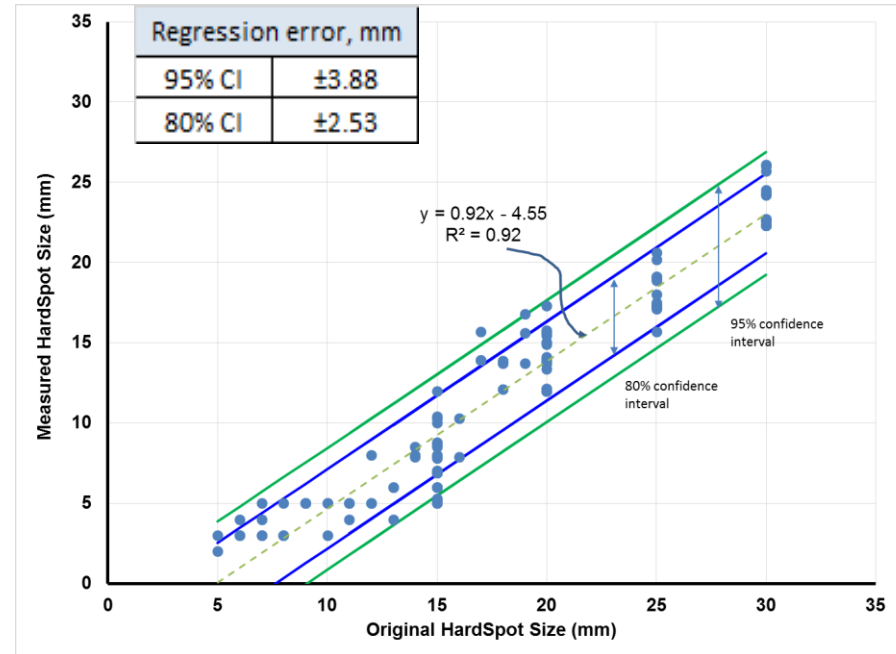
Size (mm)	Mean size (mm)	Detected size (mm)	Mean Size Error (mm)	Std. Dev	Tolerance (mm)
5<=x<=10	7.9	4.4	3.7	1.0	4.13
10<x<=15	13.2	6.9	6.3	1.5	6.99
15<x<=20	18.2	14.3	4.0	2.5	5.29
20<x<=25	24.2	18.0	6.2	1.8	8.01
25<x<=30	29.2	23.7	5.5	2.0	7.46
30<x<=40	36.7	32.5	4.2	2.2	5.58
40<x<=50	47.1	42.5	4.6	1.9	5.76
50<x<=75	63.3	58.3	5.0	1.7	5.70
Total	30.7	26.1	4.8	2.0	5.75

Mean Tolerance 5.75 mm

Regression Analysis



Along the longitudinal orientation



Along the width orientation

- 1.) Can be used to estimate the size using the regression fit
- 2.) Deviation in the detected and original size at 95% confidence interval is ± 4.18 mm

Statistical Summary

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Technologies	Overall Success rate	Binomial Probability	Tolerance (mm)	Size error for 80% CL (mm)	Mean Position Error (mm)	POFC
Provider "A"	99%	98%	5.75	2.72	2.9	0%
Provider "B"	93%	89%	5.89	6.35	1.9	1.7%
Provider "C"	93%	89%	10.83	17.21	2.6	2.5%
Provider "D"	73%	66%	26.56	21.47	14.7	31.4%
Provider "E"	81%	75%	26.81	25.93	12.4	20.7%
Provider "F"	99%	98%	9.28	10.62	3.3	0.8 %

Success rate of all the technologies are above 70%
 Tolerance in the measured size is approximately 11 mm or less for most of the technologies
 Probability of false calls is below 2-3% for most of the technologies

Specifications Summary

Technologies	Overall Success rate	Tolerance (mm)	Position Error (mm)	Optimal Speed (mm/s)	Sensor Pixel Size (mm)
Provider "A"	99%	5.75	2.9	10	20×10
Provider "B"	93%	5.89	1.9	-hand held	2×2
Provider "C"	93%	10.83	2.6	100	20×10
Provider "D"	73%	26.56	14.7	10	30×10
Provider "E"	81%	26.81	12.4	10	20×10
Provider "F"	99%	9.28	3.3	100	10×10

- 1.) Provider "C" and "F" technologies are commercial; used a scanning speed of 100 mm/s
- 2.) Provider "A" "D" and "E" used an optimum scanning speed of 10 mm/s
- 3.) Provider "B" used a hand held probe to distinguish hard spots

Variability in Speed

Technology	Speeds Used (mm/s)	Mean Size Error with Speed Variation (mm)
Provider 'A'	5,10,20	0.95
Provider 'B'	-NA (handheld probe)	-NA
Provider 'C'	50, 100, 200	0.54
Provider 'D'	5, 10, 20	2
Provider 'E'	5, 10, 20	1.9
Provider 'F'	100, 200, 300	2.1

Limited Effect

Conclusions

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- **Currently two technologies (Provider “C” and “F”) capable of scan speeds over 100 mm/s with high POD and certainty - commercial**
- **One Technology (Provider “A”) had high POD and sizing accuracy; however at a lower speed of 10mm/s.**
- **Three laboratory scale technologies (Provider “B”, “D” and “E”) showing great promise**

Future Work

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- **Further Assess the commerciality of viable NDE technologies and define operational limits**
 - All tools at predefined scanning speeds
 - Residual Magnetism
 - Lift off values reflective of plate reality
- **Hard spot impact on cracking in sour environment**
 - SSC susceptibility
 - Crack initiation

Acknowledgment

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- **Support of Dillinger Hütte (especially Mr. Carmelo Collura) for providing the facility and helping in logistics.**
- **Support of TWI in generating all the laser hardened samples.**
- **Assistance of all the participating technology providers**
 - ExxonMobil (Dr. Lang Feng)
 - Innospection (Dr. Konrad Reber)
 - Voestalpine (Dr. Karsten Feiste and Mr. Christian Stachelberger)
 - Rosen (Dr. Daniel Molenda)
 - Rohmann (Dr. Ulrich Semmler, Mr. Gerald Schneibel)
- **Assistance from ExxonMobil (Mr. Michael Belota) in conducting the micro-hardness measurements**
- **NDE 4-11 : Project Team Lead**
 - Dr. Jamey Fenske
- **Support and assistance from PRCI project manager**
 - Mr. John Lynk

QUESTIONS